Composites Lessonb مبم اللهالرحى strain y ut Taylor expansion u+ Ju  $\varphi(x_{+}\Delta n) = \varphi(x_{+}) + \frac{d\phi}{dx}\Delta x_{+}$ D+dx Du du Ol = Juda = <u>34</u> 30 Ex = -5 ٤, earin Strain Jydy = Jx + J 8xy dn.

 $\mathcal{E}_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_i} + \frac{\partial u_j}{\partial x_i} \right) = \frac{1}{2} \left( u_{i,j} + u_{j,i} \right)$ 3.2 Stress Strain Relations The generalized Hooke's law relating stress to Strain can be written as:  $G = \frac{E}{2(1+v^2)}$  $\mathcal{E}_{xx} = \frac{1}{E} \left[ \mathcal{O}_{x} - \mathcal{V} \left( \mathcal{O}_{y} + \mathcal{O}_{z} \right) \right]$  $\mathcal{E}_{yy} = \frac{1}{E} \left[ \sigma_y - \mathcal{V} (\sigma_x + \sigma_z) \right]$  $\mathcal{E}_{22} = \frac{1}{E} \left[ \overline{\sigma_2} - \mathcal{V} \left( \overline{\sigma_n} + \overline{\sigma_y} \right) \right]$  $8 \lambda 5 = \frac{\zeta \lambda 5}{C}$ 

$$\begin{cases} \mathcal{E}_{x} \\ \mathcal{E}_{y} \\ \mathcal{E}_{z} \\ \mathcal{E}_{z$$

and their components are referred to as elastic constants. Stiffness matrix is symmetric, and hence in general form it has 21 independent Constants

 $\begin{bmatrix} \sigma_{1} \\ \sigma_{2} \\ \sigma_{3} \\ \tau_{23} \\ \tau_{23} \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} C_{11} C_{12} C_{13} C_{14} C_{15} C_{16} \\ C_{12} C_{22} C_{23} C_{24} C_{25} C_{26} \\ C_{13} C_{23} C_{33} C_{34} C_{35} C_{36} \\ C_{13} C_{23} C_{33} C_{34} C_{35} C_{36} \\ C_{14} C_{24} C_{34} C_{44} C_{45} C_{46} \\ C_{15} C_{25} C_{35} C_{45} C_{55} C_{56} \\ C_{16} C_{26} C_{36} C_{46} C_{56} C_{66} \end{bmatrix} \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix}$ 

If there is one plane of material property symmetry (here, for example, the plane of symmetry is Z=0), the stress-strain  $\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \tau_{23} \\ \tau_{31} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & C_{16} \\ C_{12} & C_{22} & C_{23} & 0 & 0 & C_{26} \\ C_{13} & C_{23} & C_{33} & 0 & 0 & C_{36} \\ 0 & 0 & 0 & C_{44} & C_{45} & 0 \\ 0 & 0 & 0 & C_{45} & C_{55} & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \gamma_{23} \\ \gamma_{31} \end{bmatrix}$ relations reduce. [c] = [c]  $C_{16} C_{26} C_{36} 0$ 0 C<sub>66</sub> γ<sub>12</sub>  $S_{11} S_{12} S_{13} 0 0 S_{16}$  $\sigma_1$ ε1 S<sub>12</sub> S<sub>22</sub> S<sub>23</sub> 0 0 S<sub>26</sub> ε<sub>2</sub>  $\sigma_2$ monoclinic 0 S<sub>36</sub> S<sub>13</sub> S<sub>23</sub> S<sub>33</sub> 0 ε<sub>3</sub>  $\sigma_3$ 0 0 0 S<sub>44</sub> S<sub>45</sub> material 0  $\gamma_{23}$  $\tau_{23}$ (13 independent 0 0 S<sub>45</sub> S<sub>55</sub> 0 0  $\gamma_{31}$ τ<sub>31</sub> S<sub>16</sub> S<sub>26</sub> S<sub>36</sub> 0 0 S<sub>66</sub> elastic constants)  $\gamma_{12}$ 

$$\begin{bmatrix} \sigma_{1} \\ \sigma_{2} \\ \sigma_{3} \\ \tau_{23} \\ \tau_{31} \\ \tau_{12} \end{bmatrix} \begin{bmatrix} C_{11} C_{12} C_{13} & 0 & 0 & 0 \\ C_{12} C_{22} C_{23} & 0 & 0 & 0 \\ C_{13} C_{23} C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & C_{55} & 0 \\ 0 & 0 & 0 & 0 & C_{55} & 0 \\ 0 & 0 & 0 & 0 & C_{66} \end{bmatrix} \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix}$$

$$\begin{bmatrix} Orthotropic \\ materials \\ (9 C_{9}nstats) \\ \gamma_{12} \end{bmatrix}$$
Note that there is no intraction between normal stresses  $\mathcal{T}_{1}, \mathcal{T}_{2}, \mathcal{T}_{3}$  and shearing strains  $\mathcal{X}_{23}, \mathcal{X}_{3}, \mathcal{X}_{12}$ 



If at every point of a material there is one plane in which the mecanical properties are equal in all directions, then the material is called transversely isotropic.  $\begin{bmatrix} \sigma_{1} \\ \sigma_{2} \\ \sigma_{3} \\ \tau_{23} \\ \tau_{31} \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} C_{11} C_{12} C_{13} & 0 & 0 & 0 \\ C_{12} C_{11} C_{13} & 0 & 0 & 0 \\ C_{13} C_{13} C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 C_{44} & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 C_{44} & 0 \\ 0 & 0 & 0 & 0 & (C_{11} - C_{12})/2 \end{bmatrix} \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} C_{11} C_{12} C_{13} & 0 & 0 & 0 \\ C_{13} C_{13} C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & C_{44} & 0 \\ 0 & 0 & 0 & 0 & (C_{11} - C_{12})/2 \end{bmatrix} \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \\ \gamma_{23} \\ \gamma_{12} \end{bmatrix}$ 1-2: indefferent

## If there is an infinite number of planes of indefferent

direction in them:

$$\begin{bmatrix} \sigma_{1} \\ \sigma_{2} \\ \sigma_{3} \\ \tau_{23} \\ \tau_{31} \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} C_{11} C_{12} C_{12} & 0 & 0 & 0 \\ C_{12} C_{11} C_{12} & 0 & 0 & 0 \\ C_{12} C_{12} C_{11} & 0 & 0 & 0 \\ 0 & 0 & 0 (C_{11} - C_{12})/2 & 0 & 0 \\ 0 & 0 & 0 & 0 (C_{11} - C_{12})/2 & 0 \\ 0 & 0 & 0 & 0 & (C_{11} - C_{12})/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (C_{11} - C_{12})/2 \end{bmatrix} \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix}$$

2 indefferent plane sinfinit number

one of the major objectives in studying the strain-stress  
relations is to obtain the deformation response of the loaded  
body.  

$$\xi_1 = S_{11} \sigma_1 + S_{12} \sigma_2 + S_{13} \sigma_3 + S_{14} \tau_{23} + S_{15} \tau_{31} + S_{16} \tau_{12}$$
  
 $\xi_1 = S_{16} \sigma_1 + S_{26} \sigma_2 + S_{36} \sigma_3 + S_{46} \tau_{23} + S_{56} \tau_{31} + S_{66} \tau_{12}$   
Accordingly, for an applied Unianial stress  $\sigma_1 = \sigma$  (all other  
stresses are Zero)  
 $\xi_1 = S_{11} \sigma_2, \quad \xi_2 = S_{12} \sigma_2, \quad \xi_3 = S_{13} \sigma_3$   
 $\chi_{23} = S_{14} \sigma_2, \quad \xi_{31} = S_{15} \sigma_2, \quad \chi_{12} = S_{16} \sigma_3$   
It means that with a stress we have many  
deformation, on the other hand, because  $S_{11} \neq S_2 \neq S_3$ 

the deformation of the body in each direction is different.  
EXTENSION EXTENSION-EXTENSION COUPLING  

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \gamma_{23} \\ \gamma_{31} \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} S_{11} S_{12} S_{13} S_{14} S_{15} S_{16} \\ S_{12} S_{22} S_{23} S_{24} S_{25} S_{26} \\ S_{13} S_{23} S_{33} S_{34} S_{35} S_{36} \\ S_{14} S_{24} S_{34} S_{44} S_{45} S_{46} \\ S_{15} S_{25} S_{35} S_{45} S_{55} S_{56} \\ S_{16} S_{26} S_{36} S_{46} S_{56} S_{56} \\ S_{16} S_{12} S_{13} S_{23} : Vespose in the same direction \\ S_{12} S_{13} S_{23} : caupling between dissimilar normal stresses and stresses and normal stresses and stresse$$

$$\begin{bmatrix} S_{ij} \end{bmatrix} = \begin{bmatrix} E_1 & E_2 & E_3 & 0 & 0 & 0 \\ \frac{\nu_{12}}{E_1} & \frac{1}{E_2} & -\frac{\nu_{32}}{E_3} & 0 & 0 & 0 \\ -\frac{\nu_{13}}{E_1} & -\frac{\nu_{23}}{E_2} & \frac{1}{E_3} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_{23}} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_{31}} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_{12}} \end{bmatrix}$$

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$$S_{ij} = S_{ji} \Rightarrow \frac{\mathcal{J}_{ij}}{\mathcal{E}_i} = \frac{\mathcal{J}_{ji}}{\mathcal{E}_j}$$

 $\{ \epsilon \} = [ s ] \{ \sigma \}$ ,  $\{ \sigma \} = [ c ] \{ \epsilon \}$ 

$$C_{11} = \frac{S_{22}S_{33} - S_{23}^{2}}{S}$$

$$C_{12} = \frac{S_{13}S_{23} - S_{12}S_{33}}{S}$$

$$C_{22} = \frac{S_{33}S_{11} - S_{13}^{2}}{S}$$

$$C_{13} = \frac{S_{12}S_{23} - S_{13}S_{22}}{S}$$

$$C_{33} = \frac{S_{11}S_{22} - S_{12}^{2}}{S}$$

$$C_{23} = \frac{S_{12}S_{13} - S_{23}S_{11}}{S}$$

$$C_{44} = \frac{1}{S_{44}}, \qquad C_{55} = \frac{1}{S_{55}}, \qquad C_{66} = \frac{1}{S_{66}}$$
$$S = S_{11} S_{22} S_{33} - S_{11} S_{23}^2 - S_{22} S_{13}^2 - S_{33} S_{12}^2 + 2S_{12} S_{23} S_{13}$$

$$\begin{split} C_{11} &= \frac{1 - v_{23}v_{32}}{E_2 E_3 \Delta}, \qquad C_{22} = \frac{1 - v_{13}v_{31}}{E_1 E_3 \Delta}, \qquad C_{33} = \frac{1 - v_{12}v_{21}}{E_1 E_2 \Delta} \\ C_{12} &= \frac{v_{21} + v_{31}v_{23}}{E_2 E_3 \Delta} = \frac{v_{12} + v_{32}v_{13}}{E_1 E_3 \Delta} \\ C_{13} &= \frac{v_{31} + v_{21}v_{32}}{E_2 E_3 \Delta} = \frac{v_{13} + v_{12}v_{23}}{E_1 E_2 \Delta} \\ C_{23} &= \frac{v_{32} + v_{12}v_{31}}{E_1 E_3 \Delta} = \frac{v_{23} + v_{21}v_{13}}{E_1 E_2 \Delta} \\ C_{44} &= G_{23}, \qquad C_{55} = G_{31}, \qquad C_{66} = G_{16} \\ \Delta &= \frac{1 - v_{12}v_{21} - v_{23}v_{32} - v_{31}v_{13} - 2(v_{21}v_{32}v_{13})}{E_1 E_2 E_3} \end{split}$$