

calculation of stresses

$$\{\sigma\}_k = [\bar{Q}]_k \{\epsilon\} \rightarrow \{\epsilon\}^0 + z \{\epsilon\}^{(1)}$$

$$\{\sigma\}_k = z [\bar{Q}]_k \left\{ \begin{array}{l} -\frac{\partial^2 w_0}{\partial x^2} \\ -\frac{\partial^2 w_0}{\partial y^2} \\ -2 \frac{\partial^2 w_0}{\partial x \partial y} \end{array} \right\} \quad (6.2-14)$$

باستفاد از (6.2-3)

$$\{\sigma\}_k = \frac{z}{b} [\bar{Q}]_k [D^*] \left\{ \begin{array}{c} M \\ 0 \\ 0 \end{array} \right\} \quad (6.2-15)$$

$$(M_x = \frac{M}{b})$$

$$\sigma_{xx}^{(k)}(x, z) = \frac{M(x)z}{b} (\bar{Q}_{11}^{(k)} D_{11}^* + \bar{Q}_{12}^{(k)} D_{12}^* + \bar{Q}_{16}^{(k)} D_{16}^*)$$

$$\sigma_{yy}^{(k)}(x, z) = \frac{M(x)z}{b} (\bar{Q}_{12}^{(k)} D_{11}^* + \bar{Q}_{22}^{(k)} D_{12}^* + \bar{Q}_{26}^{(k)} D_{16}^*)$$

$$\sigma_{xy}^{(k)}(x, z) = \frac{M(x)z}{b} (\bar{Q}_{16}^{(k)} D_{11}^* + \bar{Q}_{26}^{(k)} D_{12}^* + \bar{Q}_{66}^{(k)} D_{16}^*)$$

(6.2-16)

معادلات استاتیکی ما فرض کردیم $\sigma_{22} = \sigma_{23} = \sigma_{32} = 0$ و با این فرض معادلات فضای حالت را به دست آوریم. اما در این

معادری بر این تئوری ما از ردیالوردش CLPT قابل محاسبه است.

معادلات استاتیکی
حاکم بر صلب

$$\begin{aligned} 0 &= \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + \frac{\partial \sigma_{xz}}{\partial z} \\ 0 &= \frac{\partial \sigma_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + \frac{\partial \sigma_{yz}}{\partial z} \\ 0 &= \frac{\partial \sigma_{xz}}{\partial x} + \frac{\partial \sigma_{yz}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} \end{aligned} \quad (6.2-17)$$

در این:

$$\begin{aligned} \sigma_{xz}^{(k)} &= - \int_{z_k}^z \left(\frac{\partial \sigma_{xx}^{(k)}}{\partial x} + \frac{\partial \sigma_{xy}^{(k)}}{\partial y} \right) dz + G^{(k)} \\ \sigma_{yz}^{(k)} &= - \int_{z_k}^z \left(\frac{\partial \sigma_{xy}^{(k)}}{\partial x} + \frac{\partial \sigma_{yy}^{(k)}}{\partial y} \right) dz + F^{(k)} \\ \sigma_{zz}^{(k)} &= - \int_{z_k}^z \left(\frac{\partial \sigma_{xz}^{(k)}}{\partial x} + \frac{\partial \sigma_{yz}^{(k)}}{\partial y} \right) dz + H^{(k)} \end{aligned}$$

(6.2-18)

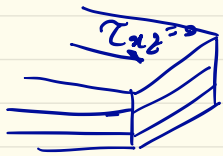
درت نمودن این ردیالورد بر این هر لایه نوشته شده است. و معادری G^k, F^k, H^k

ثابت های انترگرال بر این هر لایه هستند.

حجوں مقادیر مستقل از قلمتہ ہیں رابطہ چوتھا حدفاصلی خود. $\frac{\partial}{\partial x} = 0$ پس داریم:

$$\sigma_{xz}^{(k)}(x, z) = -Q_x(x) \left(\bar{Q}_{11}^{(k)} D_{11}^* + \bar{Q}_{12}^{(k)} D_{12}^* + \bar{Q}_{16}^{(k)} D_{16}^* \right) \left(\frac{z^2 - z_k^2}{2} \right) + G^{(k)} \quad (6.2-19)$$

$$\sigma_{zz}^{(k)}(x, z) = -\frac{dQ_x}{dx} \left(\bar{Q}_{11}^{(k)} D_{11}^* + \bar{Q}_{12}^{(k)} D_{12}^* + \bar{Q}_{16}^{(k)} D_{16}^* \right) \left(\frac{z^3 - z_k^3}{6} \right) + H^{(k)}$$

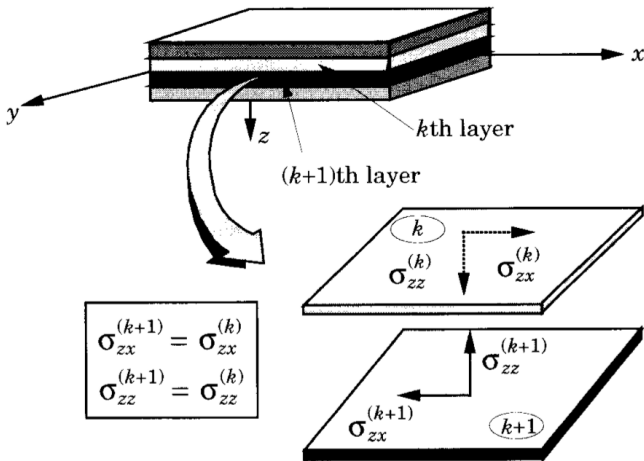


اگر سطح بالائی بدون تندی باشد (اگر تندی وجود داشته باشد $H^{(1)}$, $G^{(1)}$ قابل محاسب است)

$$G^{(1)} = 0, \quad H^{(1)} = 0$$

اگر در سطوح بعدی باید

معادلی بین تندی ها برقرار باشد



$$\sigma_{xz}^{(k)}(x, z_{k+1}) = \sigma_{xz}^{(k+1)}(x, z_{k+1}), \quad \sigma_{zz}^{(k)}(x, z_{k+1}) = \sigma_{zz}^{(k+1)}(x, z_{k+1})$$

... و 2، 3، k راضی حساب نمود

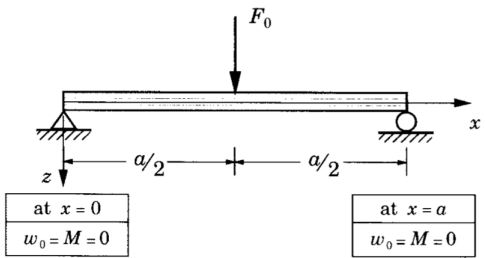
لذا می توان نامهای انتگرال

$$\begin{aligned} G^{(k+1)} &= -Q_x(x) \left(\bar{Q}_{11}^{(k)} D_{11}^* + \bar{Q}_{12}^{(k)} D_{12}^* + \bar{Q}_{16}^{(k)} D_{16}^* \right) \left(\frac{z_{k+1}^2 - z_k^2}{2} \right) + G^{(k)} \\ &= \sigma_{xz}^{(k)}(x, z_{k+1}) \end{aligned} \quad (4.2)$$

(6.2-20)

$$\begin{aligned} H^{(k+1)} &= -\frac{dQ_x}{dx} \left(\bar{Q}_{11}^{(k)} D_{11}^* + \bar{Q}_{12}^{(k)} D_{12}^* + \bar{Q}_{16}^{(k)} D_{16}^* \right) \left(\frac{z_{k+1}^3 - z_k^3}{6} \right) + H^{(k)} \\ &= \sigma_{zz}^{(k)}(x, z_{k+1}) \end{aligned} \quad (4.2)$$

three-point-bending : $\int \int$



$$M(x) = \frac{(F_0 b)x}{2}, \quad \text{for } 0 \leq x \leq \frac{a}{2}$$

into Eq. (6.2.11a) and evaluating the inte

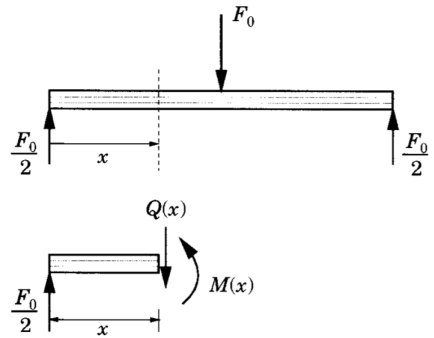
$$E_{xx}^b I_{yy} w_0(x) = -\frac{F_0 b x^3}{12} + c_1 x + c_2$$

evaluated using the boundary conditions

$$w_0(0) = 0, \quad \frac{dw_0}{dx}(a/2) = 0$$

$w_0(a/2) = 0$)

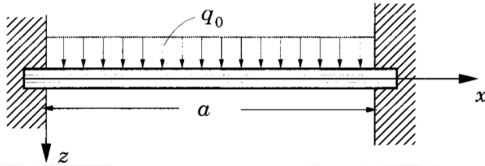
$$w_0(x) = \frac{F_0 b a^3}{48 E_{xx}^b I_{yy}} \left[3 \left(\frac{x}{a} \right) - 4 \left(\frac{x}{a} \right)^3 \right]$$



The maximum in-plane stress σ_{xx} occurs at $x = a/2$ ($M(a/2) = F_0 b a / 4$)

$$\sigma_{xx}^{(k)}(a/2, z) = \frac{F_0 a z}{4} \left(\bar{Q}_{11}^{(k)} D_{11}^* + \bar{Q}_{12}^{(k)} D_{12}^* + \bar{Q}_{16}^{(k)} D_{16}^* \right)$$

مثال:
باستاده از (ب 11-2.6) داریم:



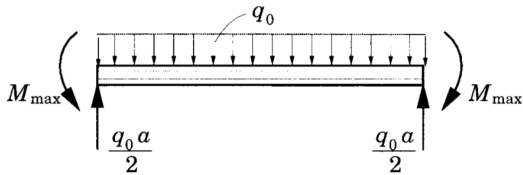
| |
|-----------------------------|
| at $x = 0$ |
| $w_0 = \frac{dw_0}{dx} = 0$ |
| or |
| $w_0 = \phi_x = 0$ |

| |
|-----------------------------|
| at $x = a$ |
| $w_0 = \frac{dw_0}{dx} = 0$ |
| or |
| $w_0 = \phi_x = 0$ |

$$E_{xx}^b I_{yy} w_0(x) = \frac{q_0 b x^4}{24} + c_1 \frac{x^3}{6} + c_2 \frac{x^2}{2} + c_3 x + c_4$$

beam. For the full beam case we have

$$w_0(0) = 0, \quad w_0(a) = 0, \quad \frac{dw_0}{dx}(0) = 0, \quad \frac{dw_0}{dx}(a) = 0$$



for the half beam model we have

$$w_0(0) = 0, \quad \frac{dw_0}{dx}(0) = 0, \quad \frac{dw_0}{dx}\left(\frac{a}{2}\right) = 0, \quad Q\left(\frac{a}{2}\right) = \frac{dM}{dx} = -E_{xx} I_{yy} \frac{d^3 w_0}{dx^3} \left(\frac{a}{2}\right) = 0$$

در نظر صرف

$$w_0(x) = \frac{q_0 b a^4}{24 E_{xx}^b I_{yy}} \left[\left(\frac{x}{a}\right)^2 - \left(\frac{x}{a}\right) \right]^2$$

$$M(x) = -\frac{q_0 b a^2}{12} \left[1 - 6 \left(\frac{x}{a} \right) + 6 \left(\frac{x}{a} \right)^2 \right], \quad M_{max} = -\frac{q_0 b a^2}{12}$$

$$\sigma_{xx}^{(k)}(0, z) = -\frac{q_0 a^2 z}{12} \left(Q_{11}^{(k)} D_{11}^* + Q_{12}^{(k)} D_{12}^* + Q_{16}^{(k)} D_{16}^* \right)$$

Laminated Beam

Deflection, $w_0(x)$

w_{max} and
 M_{max}

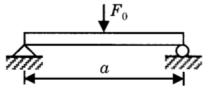
• *Hinged-Hinged*

Central point load

$$\frac{c_1}{48} \left[3 \left(\frac{x}{a} \right) - 4 \left(\frac{x}{a} \right)^3 \right]$$

$$w_{max}^c = \frac{1}{48} c_1$$

$$M_{max}^c = -\frac{1}{4} c_3$$

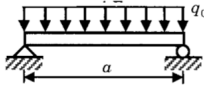


Uniform load

$$\frac{c_2}{24} \left[\left(\frac{x}{a} \right) - 2 \left(\frac{x}{a} \right)^3 + \left(\frac{x}{a} \right)^4 \right]$$

$$w_{max}^c = \frac{5}{384} c_2$$

$$M_{max}^c = -\frac{1}{8} c_4$$



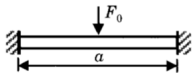
• *Fixed-Fixed*

Central point load

$$\frac{c_1}{48} \left[3 \left(\frac{x}{a} \right)^2 - 4 \left(\frac{x}{a} \right)^3 \right]$$

$$w_{max}^c = \frac{1}{192} c_1$$

$$M_{max}^0 = \frac{1}{8} c_3$$

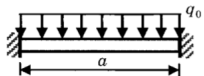


Uniform load

$$\frac{c_2}{24} \left[\left(\frac{x}{a} \right)^2 - \left(\frac{x}{a} \right)^3 \right]^2$$

$$w_{max}^c = \frac{1}{384} c_2$$

$$M_{max}^0 = \frac{1}{12} c_4$$



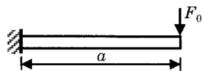
• *Fixed-Free*

Point load at free end

$$\frac{c_1}{6} \left[3 \left(\frac{x}{a} \right)^2 - \left(\frac{x}{a} \right)^3 \right]$$

$$w_{max}^a = \frac{1}{3} c_1$$

$$M_{max}^0 = c_3$$

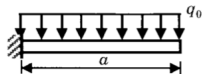


Uniform load

$$\frac{c_2}{24} \left[6 \left(\frac{x}{a} \right)^2 - 4 \left(\frac{x}{a} \right)^3 + \left(\frac{x}{a} \right)^4 \right]$$

$$w_{max}^a = \frac{1}{8} c_2$$

$$M_{max}^0 = \frac{1}{2} c_4$$



6-2-3 Buckling

کمانتی حالت ناپایداری سے کہ اگر کسی جسم تغیر شکل بعد، دوبارہ بہ حالت قبل بازنہی کر دو تغیر شکل یہ تباہی سے شہد.

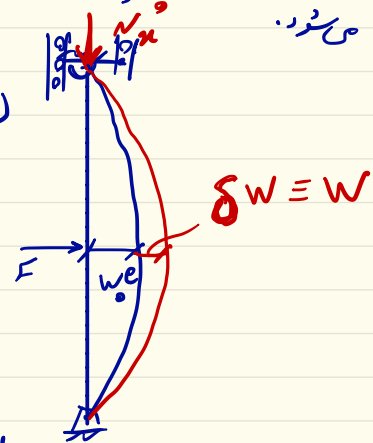
(6.2-8) =>

$$\frac{d^4 W}{dx^4} + \frac{b N_{xx}}{E_x^b I_y} \frac{d^2 W}{dx^2} = 0$$

معادله کمانتی
تیر CLPT (6.2-21)

$$w_0 = w_0^e + W \rightarrow \text{buckling deflection}$$

↳ prebuckling



معادله (6.2-21) اراں توں براں جا بجائی کل و بیسی کمانتی ہم نوکے:

$$E_{xx}^b I_{yy} \frac{d^4 w_0}{dx^4} + b N_{xx}(w_0) \frac{d^2 w_0}{dx^2} = 0 \quad (6.2-22)$$

$$E_{xx}^b I_{yy} \frac{d^4 w_0^e}{dx^4} + b N_{xx}(w_0^e) \frac{d^2 w_0^e}{dx^2} = 0 \quad (6.2-23)$$

با انتگرال گیری از (6.2-21) داریم:

$$\frac{d^2 w}{dx^2} + \frac{b N_x^0}{E_x^b I_y} w = k_1 x + k_2$$

(6.2-24) معادله تامل کلاسی
تیر CLPT

حل عمومی این معادله ضمیمه است

$$w(x) = C_1 \sin(\lambda_b x) + C_2 \cos(\lambda_b x) + C_3 x + C_4 \quad (6.2-25)$$

$$\lambda_b^2 = \frac{b N_x^0}{E_x^b I_y} \quad , \quad C_3 = \frac{k_1}{\lambda_b^2} \quad , \quad C_4 = \frac{k_2}{\lambda_b^2} \quad \text{که در آن} \quad (6.2-26)$$

مقادیر C_1, C_2 با استفاده از شرایط مرزی قابل محاسبه است.

مادرسال آن هست که λ_b را به گونه ای پیدا کنیم که $w(x)$ غیر منفی وجود آید.

پس از یافتن λ_b می توان نیروی کمانش را یافت.

$$N_x = \left(\frac{E_x^b I_y}{b} \right) \lambda_b^2 \quad (6.2-27)$$

که کمترین مقدار آن، نبرد در عملی کماتنی می باشد. و از آنجا $w(n)$ شکل مورد کمانشی را جمع می کند.

سؤال : تیردوسر صغفل

$$w_0(0) = 0, \quad w_0(a) = 0, \quad M_{xx}(0) = 0, \quad M_{xx}(a) = 0$$

onditions imply

$$W(0) = 0, \quad W(a) = 0, \quad \frac{d^2W}{dx^2}(0) = 0, \quad \frac{d^2W}{dx^2}(a) = 0$$

$$W(0) = 0 : \quad c_2 + c_4 = 0$$

$$W''(0) = 0 : \quad -c_2\lambda_b^2 = 0 \quad \text{which implies} \quad c_2 = 0, \quad c_4 = 0$$

$$W(a) = 0 : \quad c_1 \sin \lambda_b a + c_3 a = 0$$

$$W''(a) = 0 : \quad c_1 \sin \lambda_b a = 0 \quad \text{which implies} \quad c_3 = 0$$

lution, the condition

$$c_1 \sin \lambda_b a = 0 \quad \text{implies that} \quad \lambda_b a = n\pi, \quad n = 1, 2, \dots$$

oad is given by

$$bN_{xx}^0 = E_{xx}^b I_{yy} \left(\frac{n\pi}{a} \right)^2$$

e is

$$W(x) = c_1 \sin \frac{n\pi x}{a}, \quad c_1 \neq 0$$

ng load becomes ($n = 1$)

$$N_{cr} = \left(\frac{\pi}{a} \right)^2 \frac{E_{xx}^b I_{yy}}{b} = \left(\frac{\pi^2}{12} \right) \frac{E_{xx}^b h^3}{a^2}$$

ode (eigenfunction) associated with it is

$$W(x) = c_1 \sin \frac{\pi x}{a}$$

مثال: تیر دوسر گیر دار

$$w_0(0) = 0, \quad \frac{dw_0}{dx}(0) = 0, \quad w_0(a) = 0, \quad \frac{dw_0}{dx}(a) = 0$$

and as

$$W(0) = 0, \quad \frac{dW}{dx}(0) = 0, \quad W(a) = 0, \quad \frac{dW}{dx}(a) = 0$$

$$W(0) = 0: \quad c_2 + c_4 = 0$$

$$W'(0) = 0: \quad c_1 \lambda_b + c_3 = 0$$

$$W(a) = 0: \quad c_1 \sin \lambda_b a + c_2 \cos \lambda_b a + c_3 a + c_4 = 0$$

$$W'(a) = 0: \quad c_1 \lambda_b \cos \lambda_b a - c_2 \lambda_b \sin \lambda_b a + c_3 = 0$$

این چهار معادله را می توان تبدیل به دو معادله زیر نمود

$$c_1 (\sin \lambda_b a - \lambda_b a) + c_2 (\cos \lambda_b a - 1) = 0$$

$$c_1 (\cos \lambda_b a - 1) - c_2 \sin \lambda_b a = 0$$

برای داشتن جوابهای غیر صفر باید (قرصینان ضرایب صفر شود

$$0 = \begin{vmatrix} \sin \lambda_b a - \lambda_b a & \cos \lambda_b a - 1 \\ \cos \lambda_b a - 1 & -\sin \lambda_b a \end{vmatrix}$$

$$= \lambda_b a \sin \lambda_b a + 2 \cos \lambda_b a - 2$$

برای معادله، معادله مشخصه می گویند (*)

Characteristic equation

جواب معادله (*) مقادیر دیگره ماتریسی ضرب می باشد.

$$e_n = \lambda_b a$$


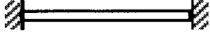

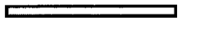
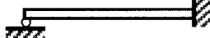
یک ردیفی برای حل معادله فوق رسم تابع $f(e_n) = e_n \sin(e_n) + 2 \cos(e_n) - 2$ است
و سپس مشاهده نمود که در چه مقادیری $f(e_n)$ صفر می شود. در هر صورت جواب تابع معادله چنین
می شود:

$$e_n = 2\pi, 8.9868, 4\pi, 15.45, 6\pi, \dots$$

پس نیرس برای این گامی می شود.

$$\begin{aligned} N_{cr} &= \left(\frac{e_n}{a}\right)^2 \left(\frac{E_{xx}^b I_{yy}}{b}\right) = \left(\frac{2\pi}{a}\right)^2 \left(\frac{E_{xx}^b I_{yy}}{b}\right) \\ &= \left(\frac{\pi^2}{3}\right) \left(\frac{E_{xx}^b h^3}{a^2}\right) \end{aligned}$$

Table 4.2.2: Values of the constants and eigenvalues for buckling of laminated composite beams with various boundary conditions ($\lambda^2 \equiv bN_{xx}^0/E_{xx}^b I_{yy} = (e_n/a)^2$). The classical laminate theory is used.

| End conditions at $x = 0$ and $x = a$ | Constants [†] | Characteristic equation and values* of $e_n \equiv \lambda_n a$ |
|--|---|--|
| <ul style="list-style-type: none"> Hinged-Hinged  | $c_1 \neq 0, c_2 = c_3 = c_4 = 0$ | $\sin e_n = 0$ $e_n = n\pi$ |
| <ul style="list-style-type: none"> Fixed-Fixed  | $c_1 = 1/(\sin e_n - e_n)$ $c_3 = -1/\lambda_n$ $c_2 = -c_4 = 1/(\cos e_n - 1)$ | $e_n \sin e_n = 2(1 - \cos e_n)$ $e_n = 2\pi, 8.987, 4\pi, \dots$ |
| <ul style="list-style-type: none"> Fixed-Free  | $c_1 = c_3 = 0$ $c_2 = -c_4 \neq 0$ | $\cos e_n = 0$ $e_n = (2n - 1)\pi/2$ |
| <ul style="list-style-type: none"> Free-Free  | $c_1 = c_3 = 0$ $c_2 \neq 0, c_4 \neq 0$ | $\sin e_n = 0$ $e_n = n\pi$ |
| <ul style="list-style-type: none"> Hinged-Fixed  | $c_1 = 1/e_n \cos e_n, c_3 = -1$ $c_2 = c_4 = 0$ | $\tan e_n = e_n$ $e_n = 4.493, 7.725, \dots$ |

[†] See Eq. (4.2.28): $W(x) = c_1 \sin \lambda_b x + c_2 \cos \lambda_b x + c_3 x + c_4$.

*For critical buckling load, only the first (minimum) value of $e = \lambda a$ is needed.