

بِسْمِ اللّٰهِ الرَّحْمٰنِ الرَّحِیْمِ

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کرنش های غیر خطی خطی بر حسب  $z$

$$\epsilon_x = \frac{\partial u_0}{\partial x} + \frac{1}{2} \left( \frac{\partial w_0}{\partial x} \right)^2 + z \frac{\partial \phi_x}{\partial x}$$

$$\epsilon_y = \frac{\partial v_0}{\partial y} + \frac{1}{2} \left( \frac{\partial w_0}{\partial y} \right)^2 + z \frac{\partial \phi_y}{\partial y}$$

$$\gamma_{xy} = \left( \frac{\partial u_0}{\partial y} + \frac{\partial v_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial w_0}{\partial y} \right) + z \left( \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \right)$$

خطی بر حسب  $z$

(5.2-4)

$$\gamma_{xz} = \frac{\partial w_0}{\partial x} + \phi_x$$

$$\gamma_{yz} = \frac{\partial w_0}{\partial y} + \phi_y$$

$$\epsilon_z = 0$$

نام بردار  $z$  (تقریب)

(5.2-5)

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{yz} \\ \gamma_{xz} \\ \gamma_{xy} \end{Bmatrix} = \begin{Bmatrix} \epsilon_x^0 \\ \epsilon_y^0 \\ \gamma_{yz}^0 \\ \gamma_{xz}^0 \\ \gamma_{xy}^0 \end{Bmatrix} + z \begin{Bmatrix} \epsilon_x^{(1)} \\ \epsilon_y^{(1)} \\ \gamma_{yz}^{(1)} \\ \gamma_{xz}^{(1)} \\ \gamma_{xy}^{(1)} \end{Bmatrix} = \begin{Bmatrix} \frac{\partial u_0}{\partial x} + \frac{1}{2} \left( \frac{\partial w_0}{\partial x} \right)^2 \\ \frac{\partial v_0}{\partial y} + \frac{1}{2} \left( \frac{\partial w_0}{\partial y} \right)^2 \\ \frac{\partial w_0}{\partial x} + \phi_x \\ \frac{\partial w_0}{\partial y} + \phi_y \\ \frac{\partial u_0}{\partial y} + \frac{\partial v_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial w_0}{\partial y} \end{Bmatrix} + z \begin{Bmatrix} \frac{\partial \phi_x}{\partial x} \\ \frac{\partial \phi_y}{\partial y} \\ 0 \\ 0 \\ \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \end{Bmatrix}$$

## 5.2.2 Equation of Motion

$$0 = \int_0^T (\delta U + \delta V - \delta K) dt \quad (5.2-6)$$

$$\delta U = \int_{\Omega_0} \left\{ \int_{-h/2}^{h/2} [\sigma_x (\delta \epsilon_x^0 + z \delta \epsilon_x^{(1)}) + \sigma_y (\delta \epsilon_y^0 + z \delta \epsilon_y^{(1)}) + \sigma_{xy} (\delta \gamma_{xy}^0 + z \delta \gamma_{xy}^{(1)}) + \sigma_{xz} \delta \gamma_{xz}^0 + \sigma_{yz} \delta \gamma_{yz}^0] dz \right\} dxdy$$

$$\delta V = - \int_{\Omega_0} [(q_b + q_z) \delta w_0] dxdy - \int_{\Gamma_0} \int_{-h/2}^{h/2} [\hat{\sigma}_n (\delta u_n + z \delta \phi_n) + \hat{\sigma}_{ns} (\delta u_s + z \delta \phi_s) + \hat{\sigma}_{nz} \delta w_0] dz ds$$

$$\delta K = \int_{\Omega_0} \int_{-h/2}^{h/2} \rho_0 \left[ (\dot{u}_0 + z \dot{\phi}_x) (\delta \dot{u}_0 + z \delta \dot{\phi}_x) + (\dot{v}_0 + z \dot{\phi}_y) (\delta \dot{v}_0 + z \delta \dot{\phi}_y) + \dot{w}_0 \delta \dot{w}_0 \right] dz dxdy$$

$$(5.2-7)$$

با جایگزینی (5.2-7) در رابطه (5.2-6) دانتگرال گیری درجهت  $z$  داریم:

$$0 = \int_0^T \left\{ \int_{\Omega_0} \left[ N_{xx} \delta \varepsilon_{xx}^{(0)} + M_{xx} \delta \varepsilon_{xx}^{(1)} + N_{yy} \delta \varepsilon_{yy}^{(0)} + M_{yy} \delta \varepsilon_{yy}^{(1)} + N_{xy} \delta \gamma_{xy}^{(0)} + M_{xy} \delta \gamma_{xy}^{(1)} \right. \right. \\ \left. \left. + Q_x \delta \gamma_{xz}^{(0)} + Q_y \delta \gamma_{yz}^{(0)} - q \delta w_0 - I_0 (\dot{u}_0 \delta \dot{u}_0 + \dot{v}_0 \delta \dot{v}_0 + \dot{w}_0 \delta \dot{w}_0) \right. \right. \\ \left. \left. - I_1 (\dot{\phi}_x \delta \dot{u}_0 + \dot{\phi}_y \delta \dot{v}_0 + \delta \dot{\phi}_x \dot{u}_0 + \delta \dot{\phi}_y \dot{v}_0) - I_2 (\dot{\phi}_x \delta \dot{\phi}_x + \dot{\phi}_y \delta \dot{\phi}_y) \right] dx dy \right. \\ \left. - \int_{\Gamma_\sigma} (\hat{N}_{nn} \delta u_n + \hat{N}_{ns} \delta u_s + \hat{M}_{nn} \delta \phi_n + \hat{M}_{ns} \delta \phi_s + \hat{Q}_n \delta w_0) ds \right\} dt \quad (3.4.9) \quad (5.2-8)$$

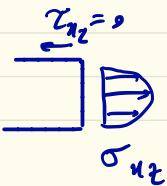
نتیجی برنی در تئوری FSDT و تا کور اصلاح نتیجی برنی

عبور معادسی داشته:

$$\begin{Bmatrix} Q_x \\ Q_y \end{Bmatrix} = \int_{-h/2}^{h/2} \begin{Bmatrix} \sigma_{xz} \\ \sigma_{yz} \end{Bmatrix} dz \quad (5.2-9)$$

یعنی در این تئوری مقدار تئوری برنی تابع در نظر گرفته می شود که برابر است!

$$\sigma_{xz} = \frac{Q_x}{A} \quad (5.2-10)$$



ایمی دانیم که در واقعیت این نتیجی توزیع درجه درم دارد (در حد اتقن)

این فرض ثابت بودن، باعث می شود انحراف کرنشی محاسبه شده دارای خطای نسبت به واقعیه باشد.  
 این خطا را با ضربی اصلاح می توان کرد.

$$\begin{Bmatrix} Q_x \\ Q_y \end{Bmatrix} = K \int_{-h/2}^{h/2} \begin{Bmatrix} \sigma_{xz} \\ \sigma_{yz} \end{Bmatrix} dz \quad (5.2-11)$$

$$K = \frac{U^C}{U^F} \quad \begin{array}{l} \text{انحراف کرنشی با استفاده از توزیع واقعی} \\ \text{انحراف کرنشی با استفاده از فرض ثابت بودن} \end{array} \quad (5.2-12)$$

مثلا بران سطح مقطع مستطیلی شکل توزیع واقعی

$$\sigma_{xz}^C = \frac{3Q}{2bh} \left[ 1 - \left( \frac{2z}{h} \right)^2 \right] \quad (5.2-13)$$

$$\Rightarrow \begin{cases} U^C = \frac{1}{2G_{13}} \int_A (\sigma_{xz}^C)^2 dA = \frac{3Q^2}{5G_{13}bh} \\ U^F = \frac{1}{2G_{13}} \int_A (\sigma_{xz}^F)^2 dA = \frac{Q^2}{3G_{13}bh} \end{cases} \quad (5.2-14)$$

$$K = \frac{U^c}{UF} = \frac{5}{6}$$

برای مقطع مستطیلی

بمرتب کردن رابطه (5.2-8) داریم:

$$\begin{aligned}
 0 = & \int_0^T \int_{\Omega_0} \left[ - (N_{xx,x} + N_{xy,y} - I_0 \ddot{u}_0 - I_1 \ddot{\phi}_x) \delta u_0 \right. \\
 & - (N_{xy,x} + N_{yy,y} - I_0 \ddot{v}_0 - I_1 \ddot{\phi}_y) \delta v_0 \\
 & - (M_{xx,x} + M_{xy,y} - Q_x - I_2 \ddot{\phi}_x - I_1 \ddot{u}_0) \delta \phi_x \\
 & - (M_{xy,x} + M_{yy,y} - Q_y - I_2 \ddot{\phi}_y - I_1 \ddot{v}_0) \delta \phi_y \\
 & \left. - (Q_{x,x} + Q_{y,y} + \mathcal{N}(w_0) + q - I_0 \ddot{w}_0) \delta w_0 \right] dx dy \\
 & + \int_0^T \int_{\Gamma} \left[ (N_{nn} - \hat{N}_{nn}) \delta u_n + (N_{ns} - \hat{N}_{ns}) \delta u_s + (Q_n - \hat{Q}_n) \delta w_0 \right. \\
 & \left. + (M_{nn} - \hat{M}_{nn}) \delta \phi_n + (M_{ns} - \hat{M}_{ns}) \delta \phi_s \right] ds dt \quad (5.2-15)
 \end{aligned}$$

که در آن

$$\mathcal{N}(w_0) = \frac{\partial}{\partial x} \left( N_{xx} \frac{\partial w_0}{\partial x} + N_{xy} \frac{\partial w_0}{\partial y} \right) + \frac{\partial}{\partial y} \left( N_{xy} \frac{\partial w_0}{\partial x} + N_{yy} \frac{\partial w_0}{\partial y} \right)$$

(5.2-16)

$$\mathcal{P}(w_0) = \left( N_{xx} \frac{\partial w_0}{\partial x} + N_{xy} \frac{\partial w_0}{\partial y} \right) n_x + \left( N_{xy} \frac{\partial w_0}{\partial x} + N_{yy} \frac{\partial w_0}{\partial y} \right) n_y$$

حال کوئین:

$$\delta u_0 : \frac{\partial N_{xx}}{\partial x} + \frac{\partial N_{xy}}{\partial y} = I_0 \frac{\partial^2 u_0}{\partial t^2} + I_1 \frac{\partial^2 \phi_x}{\partial t^2}$$

$$\delta v_0 : \frac{\partial N_{xy}}{\partial x} + \frac{\partial N_{yy}}{\partial y} = I_0 \frac{\partial^2 v_0}{\partial t^2} + I_1 \frac{\partial^2 \phi_y}{\partial t^2}$$

$$\delta w_0 : \frac{\partial Q_x}{\partial x} + \frac{\partial Q_y}{\partial y} + N(w_0) + q = I_0 \frac{\partial^2 w_0}{\partial t^2}$$

(5.2-17)

معادلات حاکم بر ورق FSDT

$$\delta \phi_x : \frac{\partial M_{xx}}{\partial x} + \frac{\partial M_{xy}}{\partial y} - Q_x = I_2 \frac{\partial^2 \phi_x}{\partial t^2} + I_1 \frac{\partial^2 u_0}{\partial t^2}$$

$$\delta \phi_y : \frac{\partial M_{xy}}{\partial x} + \frac{\partial M_{yy}}{\partial y} - Q_y = I_2 \frac{\partial^2 \phi_y}{\partial t^2} + I_1 \frac{\partial^2 v_0}{\partial t^2}$$

$u_n, u_{ns}, w_0, \phi_n, \phi_s$

متغیرهای اولیه

(5.2-18)

$N_n, N_{ns}, Q_n, M_n, M_{ns}$

متغیرهای ثانویه

لذا شرایط مرزی طبیعی (انرژی) natural B.C.

$$N_n - \hat{N}_n = 0, N_{ns} - \hat{N}_{ns} = 0, Q_n - \hat{Q}_n = 0, M_n - \hat{M}_n = 0$$

$$, M_{ns} - \hat{M}_{ns} = 0 \quad (5.2-19)$$

$$Q_n = Q_x n_x + Q_y n_y + p(w_0)$$

که در آن

## 5.2-3 Laminate Constitutive Equation

$$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_{xy} \end{Bmatrix}_k = [\bar{Q}]_k \left( \begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{Bmatrix} - \begin{Bmatrix} \alpha_x \\ \alpha_y \\ \alpha_{xy} \end{Bmatrix} \Delta T \right) - \begin{Bmatrix} 0 & 0 & \varepsilon_{13} \\ 0 & 0 & \varepsilon_{23} \\ 0 & 0 & \varepsilon_{36} \end{Bmatrix}_k \begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \varepsilon_z \end{Bmatrix}_k \quad (5.2-20)$$

قبل رسیدیم:  
با اشتغال کرنی می رسیدیم:

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \end{Bmatrix} = [A] \begin{Bmatrix} \varepsilon_x^0 \\ \varepsilon_y^0 \\ \gamma_{xy}^0 \end{Bmatrix} + [B] \begin{Bmatrix} \varepsilon_x^{(1)} \\ \varepsilon_y^{(1)} \\ \gamma_{xy}^{(1)} \end{Bmatrix} \quad (5.2-21)$$

$$\begin{Bmatrix} M_x \\ M_y \\ M_{xy} \end{Bmatrix} = [B] \begin{Bmatrix} \varepsilon_x^0 \\ \varepsilon_y^0 \\ \gamma_{xy}^0 \end{Bmatrix} + [D] \begin{Bmatrix} \varepsilon_x^{(1)} \\ \varepsilon_y^{(1)} \\ \gamma_{xy}^{(1)} \end{Bmatrix} \quad (5.2-22)$$

در تئوری FSDT ماتریس‌ها A, B, D تغییر نمی‌کنند، فقط کرنی k تغییر خواهد کرد.

$$\begin{aligned}
 \begin{Bmatrix} N_{xx} \\ N_{yy} \\ N_{xy} \end{Bmatrix} &= \begin{bmatrix} A_{11} & A_{12} & A_{16} \\ A_{12} & A_{22} & A_{26} \\ A_{16} & A_{26} & A_{66} \end{bmatrix} \begin{Bmatrix} \frac{\partial u_0}{\partial x} + \frac{1}{2} \left( \frac{\partial w_0}{\partial x} \right)^2 \\ \frac{\partial v_0}{\partial y} + \frac{1}{2} \left( \frac{\partial w_0}{\partial y} \right)^2 \\ \frac{\partial u_0}{\partial y} + \frac{\partial v_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial w_0}{\partial y} \end{Bmatrix} \\
 &+ \begin{bmatrix} B_{11} & B_{12} & B_{16} \\ B_{12} & B_{22} & B_{26} \\ B_{16} & B_{26} & B_{66} \end{bmatrix} \begin{Bmatrix} \frac{\partial \phi_x}{\partial x} \\ \frac{\partial \phi_y}{\partial y} \\ \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \end{Bmatrix} \\
 \begin{Bmatrix} M_{xx} \\ M_{yy} \\ M_{xy} \end{Bmatrix} &= \begin{bmatrix} B_{11} & B_{12} & B_{16} \\ B_{12} & B_{22} & B_{26} \\ B_{16} & B_{26} & B_{66} \end{bmatrix} \begin{Bmatrix} \frac{\partial u_0}{\partial x} + \frac{1}{2} \left( \frac{\partial w_0}{\partial x} \right)^2 \\ \frac{\partial v_0}{\partial y} + \frac{1}{2} \left( \frac{\partial w_0}{\partial y} \right)^2 \\ \frac{\partial u_0}{\partial y} + \frac{\partial v_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial w_0}{\partial y} \end{Bmatrix} \\
 &+ \begin{bmatrix} D_{11} & D_{12} & D_{16} \\ D_{12} & D_{22} & D_{26} \\ D_{16} & D_{26} & D_{66} \end{bmatrix} \begin{Bmatrix} \frac{\partial \phi_x}{\partial x} \\ \frac{\partial \phi_y}{\partial y} \\ \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \end{Bmatrix}
 \end{aligned}$$

(5.2-23)

معادلات فضای حالت در تئوری  
FSDT

$$\begin{Bmatrix} Q_y \\ Q_x \end{Bmatrix} = K \begin{bmatrix} A_{44} & A_{45} \\ A_{45} & A_{55} \end{bmatrix} \begin{Bmatrix} \frac{\partial w_0}{\partial y} + \phi_y \\ \frac{\partial w_0}{\partial x} + \phi_x \end{Bmatrix}$$



## 5-2-4 Equations of Motion in Terms of Displacements

باستاده از روابط (5.2-23) می توان روابط حرکت (5.2-17) را راجعاً جایابی های عمودی  $u_0, v_0, w_0, \phi_x, \phi_y$  می توان چنین نوشت (با در نظر گرفتن ملو خاصیت بیزدالکریبند)

$$A_{11} \left( \frac{\partial^2 u_0}{\partial x^2} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x^2} \right) + A_{12} \left( \frac{\partial^2 v_0}{\partial y \partial x} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y \partial x} \right) +$$

$$A_{16} \left( \frac{\partial^2 u_0}{\partial y \partial x} + \frac{\partial^2 v_0}{\partial x^2} + \frac{\partial^2 w_0}{\partial x^2} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y \partial x} \right) +$$

$$B_{11} \frac{\partial^2 \phi_x}{\partial x^2} + B_{12} \frac{\partial^2 \phi_y}{\partial y \partial x} + B_{16} \left( \frac{\partial^2 \phi_x}{\partial x \partial y} + \frac{\partial^2 \phi_y}{\partial x^2} \right) +$$

$$A_{16} \left( \frac{\partial^2 u_0}{\partial x \partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x \partial y} \right) + A_{26} \left( \frac{\partial^2 v_0}{\partial y^2} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y^2} \right) +$$

$$A_{66} \left( \frac{\partial^2 u_0}{\partial y^2} + \frac{\partial^2 v_0}{\partial x \partial y} + \frac{\partial^2 w_0}{\partial x \partial y} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y^2} \right) +$$

$$B_{16} \frac{\partial^2 \phi_x}{\partial x \partial y} + B_{26} \frac{\partial^2 \phi_y}{\partial y^2} + B_{66} \left( \frac{\partial^2 \phi_x}{\partial y^2} + \frac{\partial^2 \phi_y}{\partial y \partial x} \right) -$$

$$\left( \frac{\partial N_{xx}^T}{\partial x} + \frac{\partial N_{xy}^T}{\partial y} \right) - \left( \frac{\partial N_{xx}^P}{\partial x} + \frac{\partial N_{xy}^P}{\partial y} \right) = I_0 \frac{\partial^2 u_0}{\partial t^2} + I_1 \frac{\partial^2 \phi_x}{\partial t^2}$$

(5.2-24a)

$$A_{16} \left( \frac{\partial^2 u_0}{\partial x^2} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x^2} \right) + A_{26} \left( \frac{\partial^2 v_0}{\partial y \partial x} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y \partial x} \right) +$$

$$A_{66} \left( \frac{\partial^2 u_0}{\partial y \partial x} + \frac{\partial^2 v_0}{\partial x^2} + \frac{\partial^2 w_0}{\partial x^2} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y \partial x} \right) +$$

$$B_{16} \frac{\partial^2 \phi_x}{\partial x^2} + B_{26} \frac{\partial^2 \phi_y}{\partial y \partial x} + B_{66} \left( \frac{\partial^2 \phi_x}{\partial x \partial y} + \frac{\partial^2 \phi_y}{\partial x^2} \right) +$$

$$A_{12} \left( \frac{\partial^2 u_0}{\partial x \partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x \partial y} \right) + A_{22} \left( \frac{\partial^2 v_0}{\partial y^2} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y^2} \right) +$$

$$A_{26} \left( \frac{\partial^2 u_0}{\partial y^2} + \frac{\partial^2 v_0}{\partial x \partial y} + \frac{\partial^2 w_0}{\partial x \partial y} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y^2} \right) +$$

$$B_{12} \frac{\partial^2 \phi_x}{\partial x \partial y} + B_{22} \frac{\partial^2 \phi_y}{\partial y^2} + B_{26} \left( \frac{\partial^2 \phi_x}{\partial y^2} + \frac{\partial^2 \phi_y}{\partial x \partial y} \right) -$$

$$\left( \frac{\partial N_{xy}^T}{\partial x} + \frac{\partial N_{yy}^T}{\partial y} \right) - \left( \frac{\partial N_{xy}^P}{\partial x} + \frac{\partial N_{yy}^P}{\partial y} \right) = I_0 \frac{\partial^2 v_0}{\partial t^2} + I_1 \frac{\partial^2 \phi_y}{\partial t^2}$$

(5.2-24b)

$$K A_{55} \left( \frac{\partial^2 w_0}{\partial x^2} + \frac{\partial \phi_x}{\partial x} \right) + K A_{45} \left( \frac{\partial^2 w_0}{\partial y \partial x} + \frac{\partial \phi_y}{\partial x} \right) +$$

$$K A_{45} \left( \frac{\partial^2 w_0}{\partial x \partial y} + \frac{\partial \phi_x}{\partial y} \right) + K A_{44} \left( \frac{\partial^2 w_0}{\partial y^2} + \frac{\partial \phi_y}{\partial y} \right) +$$

$$\mathcal{N}(w) + q - \left( \frac{\partial Q_x^P}{\partial x} + \frac{\partial Q_y^P}{\partial y} \right) = I_0 \frac{\partial^2 w_0}{\partial t^2}$$

(5.2-24c)

$$\begin{aligned}
& B_{11} \left( \frac{\partial^2 u_0}{\partial x^2} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x^2} \right) + B_{12} \left( \frac{\partial^2 v_0}{\partial y \partial x} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y \partial x} \right) + \\
& B_{16} \left( \frac{\partial^2 u_0}{\partial y \partial x} + \frac{\partial^2 v_0}{\partial x^2} + \frac{\partial^2 w_0}{\partial x^2} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y \partial x} \right) + \\
& D_{11} \frac{\partial^2 \phi_x}{\partial x^2} + D_{12} \frac{\partial^2 \phi_y}{\partial y \partial x} + D_{16} \left( \frac{\partial^2 \phi_x}{\partial x \partial y} + \frac{\partial^2 \phi_y}{\partial x^2} \right) + \\
& B_{16} \left( \frac{\partial^2 u_0}{\partial x \partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x \partial y} \right) + B_{26} \left( \frac{\partial^2 v_0}{\partial y^2} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y^2} \right) + \\
& B_{66} \left( \frac{\partial^2 u_0}{\partial y^2} + \frac{\partial^2 v_0}{\partial x \partial y} + \frac{\partial^2 w_0}{\partial x \partial y} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y^2} \right) + \\
& D_{16} \frac{\partial^2 \phi_x}{\partial x \partial y} + D_{26} \frac{\partial^2 \phi_y}{\partial y^2} + D_{66} \left( \frac{\partial^2 \phi_x}{\partial y^2} + \frac{\partial^2 \phi_y}{\partial y \partial x} \right) - \\
& K A_{55} \left( \frac{\partial w_0}{\partial x} + \phi_x \right) - K A_{45} \left( \frac{\partial w_0}{\partial y} + \phi_y \right) - \\
& \left( \frac{\partial M_{xx}^T}{\partial x} + \frac{\partial M_{xy}^T}{\partial y} \right) - \left( \frac{\partial M_{xx}^P}{\partial x} + \frac{\partial M_{xy}^P}{\partial y} - Q_x^P \right) \\
& = I_2 \frac{\partial^2 \phi_x}{\partial t^2} + I_1 \frac{\partial^2 u_0}{\partial t^2}
\end{aligned}$$

(5.2-24d)

$$\begin{aligned}
& B_{16} \left( \frac{\partial^2 u_0}{\partial x^2} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x^2} \right) + B_{26} \left( \frac{\partial^2 v_0}{\partial y \partial x} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y \partial x} \right) + \\
& B_{66} \left( \frac{\partial^2 u_0}{\partial y \partial x} + \frac{\partial^2 v_0}{\partial x^2} + \frac{\partial^2 w_0}{\partial x^2} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y \partial x} \right) + \\
& D_{16} \frac{\partial^2 \phi_x}{\partial x^2} + D_{26} \frac{\partial^2 \phi_y}{\partial y \partial x} + D_{66} \left( \frac{\partial^2 \phi_x}{\partial x \partial y} + \frac{\partial^2 \phi_y}{\partial x^2} \right) + \\
& B_{12} \left( \frac{\partial^2 u_0}{\partial x \partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial x \partial y} \right) + B_{22} \left( \frac{\partial^2 v_0}{\partial y^2} + \frac{\partial w_0}{\partial y} \frac{\partial^2 w_0}{\partial y^2} \right) + \\
& B_{26} \left( \frac{\partial^2 u_0}{\partial y^2} + \frac{\partial^2 v_0}{\partial x \partial y} + \frac{\partial^2 w_0}{\partial x \partial y} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial^2 w_0}{\partial y^2} \right) + \\
& D_{12} \frac{\partial^2 \phi_x}{\partial x \partial y} + D_{22} \frac{\partial^2 \phi_y}{\partial y^2} + D_{26} \left( \frac{\partial^2 \phi_x}{\partial y^2} + \frac{\partial^2 \phi_y}{\partial x \partial y} \right) - \\
& K A_{45} \left( \frac{\partial w_0}{\partial x} + \phi_x \right) - K A_{44} \left( \frac{\partial w_0}{\partial y} + \phi_y \right) - \\
& \left( \frac{\partial M_{xy}^T}{\partial x} + \frac{\partial M_{yy}^T}{\partial y} \right) - \left( \frac{\partial M_{xy}^P}{\partial x} + \frac{\partial M_{yy}^P}{\partial y} - Q_y^P \right) \\
& = I_2 \frac{\partial^2 \phi_y}{\partial t^2} + I_1 \frac{\partial^2 v_0}{\partial t^2}
\end{aligned}$$

(5.2-24e)

# مسئله : خمشی استوانه‌ای (cylindrical bending) در رکنور FSDT خمشی فصولی شود

$$A_{11} \frac{\partial^2 u_0}{\partial x^2} + A_{16} \frac{\partial^2 v_0}{\partial x^2} + B_{11} \frac{\partial^2 \phi_x}{\partial x^2} + B_{16} \frac{\partial^2 \phi_y}{\partial x^2} - \frac{\partial N_{xx}^T}{\partial x} - \frac{\partial N_{xx}^P}{\partial x} = I_0 \frac{\partial^2 u_0}{\partial t^2} + I_1 \frac{\partial^2 \phi_x}{\partial t^2}$$

$$(a) \quad \frac{\partial}{\partial y} = 0$$

$$A_{16} \frac{\partial^2 u_0}{\partial x^2} + A_{66} \frac{\partial^2 v_0}{\partial x^2} + B_{16} \frac{\partial^2 \phi_x}{\partial x^2} + B_{66} \frac{\partial^2 \phi_y}{\partial x^2} - \frac{\partial N_{xy}^T}{\partial x} - \frac{\partial N_{xy}^P}{\partial x} = I_0 \frac{\partial^2 v_0}{\partial t^2} + I_1 \frac{\partial^2 \phi_y}{\partial t^2}$$

(b)

$$B_{11} \frac{\partial^2 u_0}{\partial x^2} + B_{16} \frac{\partial^2 v_0}{\partial x^2} + D_{11} \frac{\partial^2 \phi_x}{\partial x^2} + D_{16} \frac{\partial^2 \phi_y}{\partial x^2} - K A_{55} \left( \frac{\partial w_0}{\partial x} + \phi_x \right) - K A_{45} \phi_y - \frac{\partial M_{xx}^T}{\partial x} - \frac{\partial M_{xx}^P}{\partial x} + Q_x^P = I_2 \frac{\partial^2 \phi_x}{\partial t^2} + I_1 \frac{\partial^2 u_0}{\partial t^2}$$

(c)

$$B_{16} \frac{\partial^2 u_0}{\partial x^2} + B_{66} \frac{\partial^2 v_0}{\partial x^2} + D_{16} \frac{\partial^2 \phi_x}{\partial x^2} + D_{66} \frac{\partial^2 \phi_y}{\partial x^2} - K A_{44} \phi_y - K A_{45} \left( \frac{\partial w_0}{\partial x} + \phi_x \right) - \frac{\partial M_{xy}^T}{\partial x} - \frac{\partial M_{xy}^P}{\partial x} + Q_y^P = I_2 \frac{\partial^2 \phi_y}{\partial t^2} + I_1 \frac{\partial^2 v_0}{\partial t^2}$$

(d)

$$K A_{55} \left( \frac{\partial^2 w_0}{\partial x^2} + \frac{\partial \phi_x}{\partial x} \right) + K A_{45} \frac{\partial \phi_y}{\partial x} + \frac{\partial}{\partial x} \left( N_{xx} \frac{\partial w_0}{\partial x} \right) + q - \frac{\partial Q_x^P}{\partial x} = I_0 \frac{\partial^2 w_0}{\partial t^2}$$

(e)