

بِسْمِ اللّٰهِ الرَّحْمٰنِ الرَّحِیْمِ

مواد مرکب

جلد ۱۸

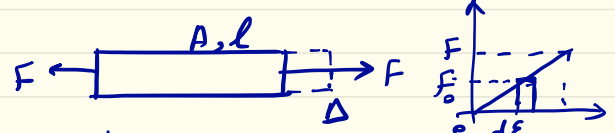
δU

انرژی کرنشی مجازی

$$\delta U = \int_V \{\sigma\}^T \cdot \{\delta \epsilon\} dV$$

$$= \int_{\Omega_0} \int_{-h/2}^{h/2} (\sigma_x \delta \epsilon_x + \sigma_y \delta \epsilon_y + 2\sigma_{xy} \delta \epsilon_{xy}) dz dndy$$

$$= \int_{\Omega_0} \int_{-h/2}^{h/2} \left[\sigma_x (\delta \epsilon_x^0 + z \delta \epsilon_x^{(1)}) + \sigma_y (\delta \epsilon_y^0 + z \delta \epsilon_y^{(1)}) + \sigma_{xy} (\delta \gamma_{xy}^0 + z \delta \gamma_{xy}^{(1)}) \right] dz dndy \quad (5.1-12)$$

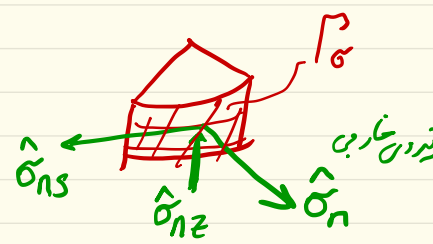
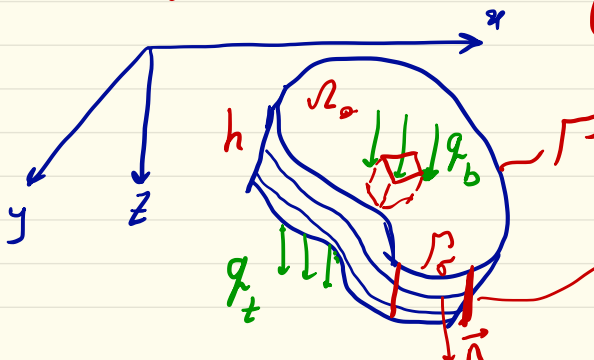


$$W = F \cdot \Delta \rightarrow W_0 = \frac{W}{V} = \frac{F \cdot \Delta}{A \cdot l}$$

$$W_0 = \sigma \cdot \epsilon \rightarrow dW_0 = \sigma \cdot d\epsilon$$

$$\delta U_0 = \sigma \delta \epsilon$$

$$\delta U = \int \delta U_0 dV$$



δV منفی کار انجام شده توسط نیروهای خارجی = انرژی پتانسیل نیروهای خارجی مجازی

$$V = \vec{F} \cdot \vec{u} \quad \leadsto \quad \delta V = \vec{F} \cdot \delta \vec{u}$$

$$\delta V = - \int_{\Omega_0} \left[q_b(x, y) \delta w(x, y, h/2) + q_t(x, y) \delta w(x, y, -h/2) \right] dx dy$$

$$- \int_{\Gamma_\sigma} \int_{-h/2}^{h/2} \left[\hat{\sigma}_n^{\wedge} \delta u_n + \hat{\sigma}_{ns}^{\wedge} \delta u_s + \hat{\sigma}_{nz}^{\wedge} \delta w \right] dz ds$$

$$= \int_{\Omega_0} \left[(q_b(x, y) + q_t(x, y)) \delta w_0(x, y) \right] dx dy$$

$$- \int_{\Gamma_\sigma} \int_{-h/2}^{h/2} \left[\hat{\sigma}_n^{\wedge} \left(\delta u_n - z \frac{\partial \delta w_0}{\partial n} \right) + \hat{\sigma}_{ns}^{\wedge} \left(\delta u_{os} - z \frac{\partial \delta w_0}{\partial s} \right) + \hat{\sigma}_{nz}^{\wedge} \delta w_0 \right] dz ds \quad (5.1-13)$$

δK

انرژی جنبشی مجاز

$$K = \int_V \frac{1}{2} \rho (\dot{u}^2 + \dot{v}^2 + \dot{w}^2) d\tau \rightarrow \delta K = \int_V \rho (\dot{u} \delta u + \dot{v} \delta v + \dot{w} \delta w) d\tau$$

$$\delta K = \int_{z_0 - \frac{h}{2}}^{z_0 + \frac{h}{2}} \rho_0 \left[\left(\dot{u}_0 - z \frac{\partial \dot{w}_0}{\partial x} \right) \left(\delta \dot{u}_0 - z \frac{\partial \delta \dot{w}_0}{\partial x} \right) + \left(\dot{v}_0 - z \frac{\partial \dot{w}_0}{\partial y} \right) \left(\delta \dot{v}_0 - z \frac{\partial \delta \dot{w}_0}{\partial y} \right) + \dot{w}_0 \delta \dot{w}_0 \right] dz dx dy \quad (5.1-14)$$

ردابطه (5.1-12) و (5.1-14) را در رابطه (5.1-11) قرار می دهیم:

$$\begin{aligned}
0 = \int_0^T \left\{ \int_{\Omega_0} \left[N_{xx} \delta \varepsilon_{xx}^{(0)} + M_{xx} \delta \varepsilon_{xx}^{(1)} + N_{yy} \delta \varepsilon_{yy}^{(0)} + M_{yy} \delta \varepsilon_{yy}^{(1)} + N_{xy} \delta \gamma_{xy}^{(0)} \right. \right. \\
+ M_{xy} \delta \gamma_{xy}^{(1)} - q \delta w_0 - I_0 (\dot{u}_0 \delta \dot{u}_0 + \dot{v}_0 \delta \dot{v}_0 + \dot{w}_0 \delta \dot{w}_0) \\
+ I_1 \left(\frac{\partial \delta \dot{w}_0}{\partial x} \dot{u}_0 + \frac{\partial \dot{w}_0}{\partial x} \delta \dot{u}_0 + \frac{\partial \delta \dot{w}_0}{\partial y} \dot{v}_0 + \frac{\partial \dot{w}_0}{\partial y} \delta \dot{v}_0 \right) \\
\left. \left. - I_2 \left(\frac{\partial \dot{w}_0}{\partial x} \frac{\partial \delta \dot{w}_0}{\partial x} + \frac{\partial \dot{w}_0}{\partial y} \frac{\partial \delta \dot{w}_0}{\partial y} \right) \right] dx dy \right. \\
\left. - \int_{\Gamma_\sigma} \left(\hat{N}_{nn} \delta u_{0n} + \hat{N}_{ns} \delta u_{0s} - \hat{M}_{nn} \frac{\partial \delta w_0}{\partial n} - \hat{M}_{ns} \frac{\partial \delta w_0}{\partial s} + \hat{Q}_n \delta w_0 \right) ds \right\} dt
\end{aligned}$$

(3.1-15)

عبارت مزی

در رابطه فوق داریم:

$$\begin{Bmatrix} N_{xx} \\ N_{yy} \\ N_{xy} \end{Bmatrix} = \int_{-\frac{h}{2}}^{\frac{h}{2}} \begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} dz, \quad \begin{Bmatrix} M_{xx} \\ M_{yy} \\ M_{xy} \end{Bmatrix} = \int_{-\frac{h}{2}}^{\frac{h}{2}} \begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} z dz$$

$$\begin{Bmatrix} \hat{N}_{nn} \\ \hat{N}_{ns} \end{Bmatrix} = \int_{-\frac{h}{2}}^{\frac{h}{2}} \begin{Bmatrix} \hat{\sigma}_{nn} \\ \hat{\sigma}_{ns} \end{Bmatrix} dz, \quad \begin{Bmatrix} \hat{M}_{nn} \\ \hat{M}_{ns} \end{Bmatrix} = \int_{-\frac{h}{2}}^{\frac{h}{2}} \begin{Bmatrix} \hat{\sigma}_{nn} \\ \hat{\sigma}_{ns} \end{Bmatrix} z dz$$

$$\begin{Bmatrix} I_0 \\ I_1 \\ I_2 \end{Bmatrix} = \int_{-\frac{h}{2}}^{\frac{h}{2}} \begin{Bmatrix} 1 \\ z \\ z^2 \end{Bmatrix} \rho_0 dz, \quad \hat{Q}_n = \int_{-\frac{h}{2}}^{\frac{h}{2}} \hat{\sigma}_{nz} dz$$

(3.1-16)

حال با استفاده از رابطه (6-1-5) داریم:

$$\delta \varepsilon_x^a = \frac{\partial \delta u_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial \delta w_0}{\partial x}$$

$$\delta \varepsilon_x^{(1)} = -\frac{\partial^2 \delta w_0}{\partial x^2}$$

$$\delta \varepsilon_y^a = \frac{\partial \delta v_0}{\partial y} + \frac{\partial w_0}{\partial y} \frac{\partial \delta w_0}{\partial y}$$

$$\delta \varepsilon_y^{(1)} = -\frac{\partial^2 \delta w_0}{\partial y^2}$$

$$\delta \gamma_{xy}^a = \frac{\partial \delta u_0}{\partial y} + \frac{\partial \delta v_0}{\partial x} + \frac{\partial \delta w_0}{\partial x} \frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial x} \frac{\partial \delta w_0}{\partial y}, \quad \delta \gamma_{xy}^{(1)} = -2 \frac{\partial^2 \delta w_0}{\partial x \partial y}$$

با جایگزین این رابطه در رابطه (5.1-15) داریم:

(5.1-17)

$$\begin{aligned}
0 = & \int_0^T \left\{ \int_{\Omega_0} \left[-N_{xx,x} \delta u_0 - \left(N_{xx} \frac{\partial w_0}{\partial x} \right)_{,x} \delta w_0 - M_{xx,xx} \delta w_0 - N_{yy,y} \delta v_0 \right. \right. \\
& - \left(N_{yy} \frac{\partial w_0}{\partial y} \right)_{,y} \delta w_0 - M_{yy,yy} \delta w_0 - N_{xy,y} \delta u_0 - N_{xy,x} \delta v_0 \\
& - \left(N_{xy} \frac{\partial w_0}{\partial y} \right)_{,x} \delta w_0 - \left(N_{xy} \frac{\partial w_0}{\partial x} \right)_{,y} \delta w_0 - 2M_{xy,xy} \delta w_0 - q \delta w_0 \\
& + I_0 (\ddot{u}_0 \delta u_0 + \ddot{v}_0 \delta v_0 + \ddot{w}_0 \delta w_0) - I_2 \left(\frac{\partial^2 \ddot{w}_0}{\partial x^2} + \frac{\partial^2 \ddot{w}_0}{\partial y^2} \right) \delta w_0 \\
& \left. + I_1 \left(\frac{\partial \ddot{u}_0}{\partial x} \delta w_0 - \frac{\partial \ddot{w}_0}{\partial x} \delta u_0 + \frac{\partial \ddot{v}_0}{\partial y} \delta w_0 - \frac{\partial \ddot{w}_0}{\partial y} \delta v_0 \right) \right] dx dy \\
& + \oint_{\Gamma} \left[N_{xx} n_x \delta u_0 + \left(N_{xx} \frac{\partial w_0}{\partial x} \right) n_x \delta w_0 - M_{xx} n_x \frac{\partial \delta w_0}{\partial x} + M_{xx,x} n_x \delta w_0 \right. \\
& + N_{yy} n_y \delta v_0 + \left(N_{yy} \frac{\partial w_0}{\partial y} \right) n_y \delta w_0 - M_{yy} n_y \frac{\partial \delta w_0}{\partial y} + M_{yy,y} n_y \delta w_0 \\
& - M_{xy} n_x \frac{\partial \delta w_0}{\partial y} + M_{xy,x} n_y \delta w_0 - M_{xy} n_y \frac{\partial \delta w_0}{\partial x} + M_{xy,y} n_x \delta w_0 \\
& \left. + N_{xy} n_y \delta u_0 + N_{xy} n_x \delta v_0 + N_{xy} \frac{\partial w_0}{\partial y} n_x \delta w_0 + N_{xy} \frac{\partial w_0}{\partial x} n_y \delta w_0 \right] ds \\
& - \int_{\Gamma_\sigma} \left(\hat{N}_{nn} \delta u_{0n} + \hat{N}_{ns} \delta u_{0s} - \hat{M}_{nn} \frac{\partial \delta w_0}{\partial n} - \hat{M}_{ns} \frac{\partial \delta w_0}{\partial s} + \hat{Q}_n \delta w_0 \right) ds \\
& \left. + \oint_{\Gamma} \left[-I_1 (\ddot{u}_0 n_x + \ddot{v}_0 n_y) + I_2 \left(\frac{\partial \ddot{w}_0}{\partial x} n_x + \frac{\partial \ddot{w}_0}{\partial y} n_y \right) \right] \delta w_0 ds \right\} dt \quad (3.3.22)
\end{aligned}$$

(5.1-18)

باکی مرتب سازی داریم:

$$\begin{aligned}
 0 = \int_0^T \left\{ \int_{\Omega_0} \left[- \left(N_{xx,x} + N_{xy,y} - I_0 \ddot{u}_0 + I_1 \frac{\partial \ddot{w}_0}{\partial x} \right) \delta u_0 \right. \right. \\
 - \left(N_{xy,x} + N_{yy,y} - I_0 \ddot{v}_0 + I_1 \frac{\partial \ddot{w}_0}{\partial y} \right) \delta v_0 \\
 - \left(M_{xx,xx} + 2M_{xy,xy} + M_{yy,yy} + \mathcal{N}(w_0) + q \right. \\
 \left. \left. - I_0 \ddot{w}_0 - I_1 \frac{\partial \ddot{u}_0}{\partial x} - I_1 \frac{\partial \ddot{v}_0}{\partial y} + I_2 \frac{\partial^2 \ddot{w}_0}{\partial x^2} + I_2 \frac{\partial^2 \ddot{w}_0}{\partial y^2} \right) \delta w_0 \right] dx dy \\
 + \int_{\Gamma_\sigma} \left[(N_{xx} n_x + N_{xy} n_y) \delta u_0 + (N_{xy} n_x + N_{yy} n_y) \delta v_0 \right. \\
 + \left(M_{xx,x} n_x + M_{xy,y} n_x + M_{yy,y} n_y + M_{xy,x} n_y + \mathcal{P}(w_0) \right. \\
 \left. - I_1 \ddot{u}_0 n_x - I_1 \ddot{v}_0 n_y + I_2 \frac{\partial \ddot{w}_0}{\partial x} n_x + I_2 \frac{\partial \ddot{w}_0}{\partial y} n_y \right) \delta w_0 \\
 \left. - (M_{xx} n_x + M_{xy} n_y) \frac{\partial \delta w_0}{\partial x} - (M_{xy} n_x + M_{yy} n_y) \frac{\partial \delta w_0}{\partial y} \right] ds \\
 \left. - \int_{\Gamma_\sigma} \left(\hat{N}_{nn} \delta u_{0n} + \hat{N}_{ns} \delta u_{0s} - \hat{M}_{nn} \frac{\partial \delta w_0}{\partial n} - \hat{M}_{ns} \frac{\partial \delta w_0}{\partial s} + \hat{Q}_n \delta w_0 \right) ds \right\} dt
 \end{aligned}$$

(5.1-19)

$$\mathcal{N}(w_0) = \frac{\partial}{\partial x} \left(N_{xx} \frac{\partial w_0}{\partial x} + N_{xy} \frac{\partial w_0}{\partial y} \right) + \frac{\partial}{\partial y} \left(N_{xy} \frac{\partial w_0}{\partial x} + N_{yy} \frac{\partial w_0}{\partial y} \right)$$

(5.1-20)

$$\mathcal{P}(w_0) = \left(N_{xx} \frac{\partial w_0}{\partial x} + N_{xy} \frac{\partial w_0}{\partial y} \right) n_x + \left(N_{xy} \frac{\partial w_0}{\partial x} + N_{yy} \frac{\partial w_0}{\partial y} \right) n_y$$

الرحاله حقی در نظر گرفته شود صادر \mathcal{N} و \mathcal{P} صغری شوند.

پس داریم:

(5.1-21)

معادلات حاکم بردار CLPT

δu_0 :

$$\frac{\partial N_x}{\partial x} + \frac{\partial N_{xy}}{\partial y} = I_0 \frac{\partial^2 u_0}{\partial t^2} - I_1 \frac{\partial^2}{\partial t^2} \left(\frac{\partial w_0}{\partial x} \right)$$

δv_0 :

$$\frac{\partial N_{xy}}{\partial x} + \frac{\partial N_y}{\partial y} = I_0 \frac{\partial^2 v_0}{\partial t^2} - I_1 \frac{\partial^2}{\partial t^2} \left(\frac{\partial w_0}{\partial y} \right)$$

δw_0 :

$$\frac{\partial^2 M_x}{\partial x^2} + 2 \frac{\partial^2 M_{xy}}{\partial x \partial y} + \frac{\partial^2 M_y}{\partial y^2} + N(w_0) + q = I_0 \frac{\partial^2 w_0}{\partial t^2} - I_2 \frac{\partial^2}{\partial t^2} \left(\frac{\partial^2 w_0}{\partial x^2} + \frac{\partial^2 w_0}{\partial y^2} \right) + I_1 \frac{\partial^2}{\partial t^2} \left(\frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} \right)$$