

بسم الله الرحمن الرحيم

موارد کے

جلہ ۱۷

Chapter 5: classical and First-order Theories

فرمی عکوس:

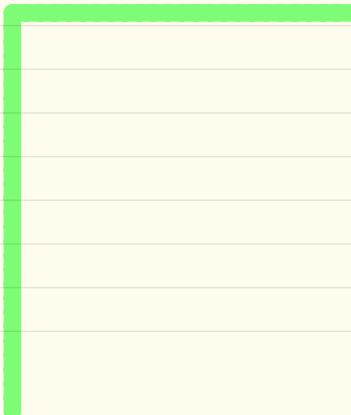
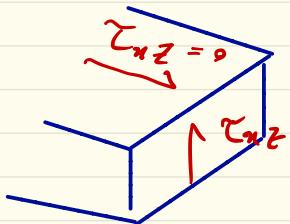
۱- تمام لایہا بعورتے کامل ہم متعال ہوتے۔

۲- مواڑ تکلیں دھنہ لایہا الاستیں خلی ہستہ و ہمین ارتور دی ہی باشندہ۔

۳- مناسنے لایہ ہاتا بے اسے

۴- تغیراتیں ہائی کر جپ

۵- تنٹی بڑی در صفحہ مرزی بالادیاںیں صورت سے



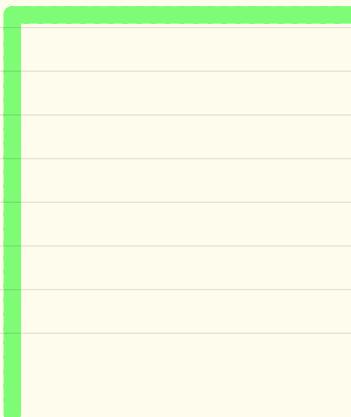
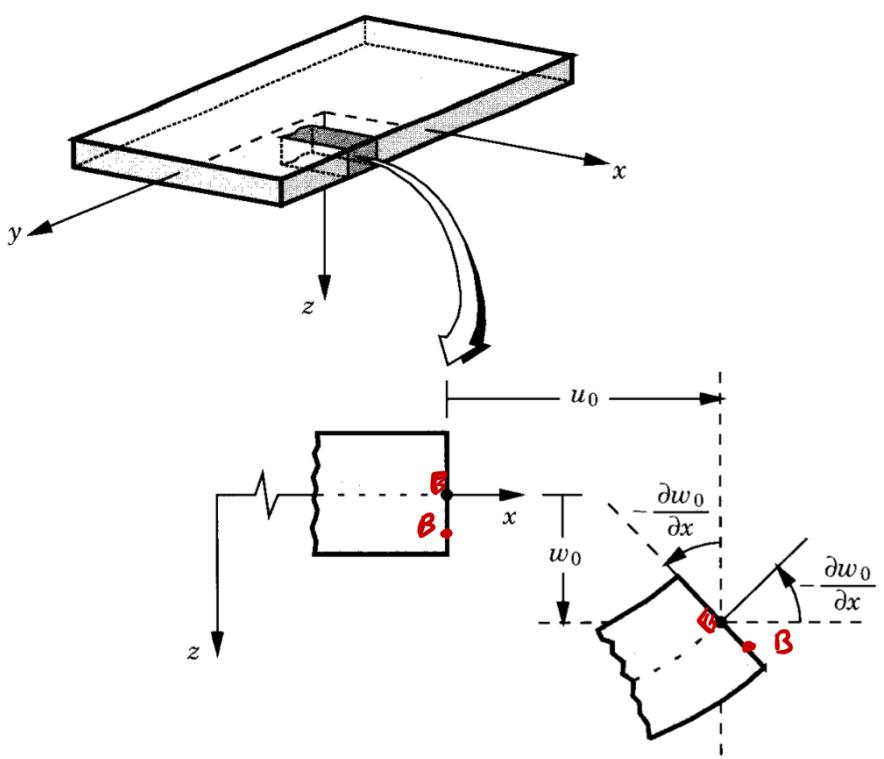
5.1. The classical Laminated Plate Theory (CLPT)

5.1.1. Displacements and Strains

$$\begin{aligned} u(x, y, z, t) &= u_0(x, y, t) - z \frac{\partial w_0}{\partial x} \\ v(x, y, z, t) &= v_0(x, y, t) - z \frac{\partial w_0}{\partial y} \\ w(x, y, z, t) &= w_0(x, y, t) \end{aligned} \quad (5.1-1)$$

فرضیات:

- 1- سطح صافی عمود بر سطح میانی بعد از تغیر شکل صافی دمودر سطح میانی باقی می‌ماند.
- 2- تغیر شکل هادرجه مقامه قابل معرفت کردن است (≈ 0.0004)



کرنشی های غیر خالی:

(5.1-2)

$$E_{xx} = \frac{\partial u}{\partial x} + \frac{1}{2} \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial w}{\partial x} \right)^2 \right]$$

$$E_{yy} = \frac{\partial v}{\partial y} + \frac{1}{2} \left[\left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial y} \right)^2 \right]$$

$$E_{zz} = \frac{\partial w}{\partial z} + \frac{1}{2} \left[\left(\frac{\partial u}{\partial z} \right)^2 + \left(\frac{\partial v}{\partial z} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 \right]$$

$$E_{xy} = \frac{1}{2} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial w}{\partial x} \frac{\partial w}{\partial y} \right)$$

$$E_{xz} = \frac{1}{2} \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial z} + \frac{\partial v}{\partial x} \frac{\partial v}{\partial z} + \frac{\partial w}{\partial x} \frac{\partial w}{\partial z} \right)$$

$$E_{yz} = \frac{1}{2} \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} + \frac{\partial u}{\partial y} \frac{\partial u}{\partial z} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \frac{\partial w}{\partial z} \right)$$

$$\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}, \frac{\partial w}{\partial z} = O(E) \quad (5.1-3)$$

اما مقادیر زیر درم 2 خطا هسته (ماکل صریح کردن)

trains. Terms of order ϵ^2 are

$$\begin{aligned} & \left(\frac{\partial u}{\partial x}\right)^2, \left(\frac{\partial u}{\partial y}\right)^2, \left(\frac{\partial u}{\partial z}\right)^2, \left(\frac{\partial u}{\partial x}\right)\left(\frac{\partial u}{\partial y}\right), \left(\frac{\partial u}{\partial x}\right)\left(\frac{\partial u}{\partial z}\right), \left(\frac{\partial u}{\partial y}\right)\left(\frac{\partial u}{\partial z}\right) \\ & \left(\frac{\partial v}{\partial x}\right)^2, \left(\frac{\partial v}{\partial y}\right)^2, \left(\frac{\partial v}{\partial z}\right)^2, \left(\frac{\partial v}{\partial x}\right)\left(\frac{\partial v}{\partial y}\right), \left(\frac{\partial v}{\partial x}\right)\left(\frac{\partial v}{\partial z}\right), \left(\frac{\partial v}{\partial y}\right)\left(\frac{\partial v}{\partial z}\right) \\ & \left(\frac{\partial w}{\partial x}\right)\left(\frac{\partial w}{\partial z}\right), \left(\frac{\partial w}{\partial y}\right)\left(\frac{\partial w}{\partial z}\right), \left(\frac{\partial w}{\partial z}\right)^2 \end{aligned}$$

(5.1-4)

مقادیر با اینه کرحد هسته اما مکل صریح کردن نیستد

$$\left(\frac{\partial w}{\partial x} \right)^2, \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}$$

درنتیه برس کرتنی عادی خنی هار کو میس نوائ لعه زکر شتی های غیرعلقی

$$\epsilon_{xx} = \frac{\partial u}{\partial x} + \frac{1}{2} \left(\frac{\partial w}{\partial x} \right)^2, \quad \epsilon_{yy} = \frac{1}{2} \left(\frac{\partial u}{\partial y} + \frac{\partial w}{\partial y} + \frac{\partial w}{\partial x} \right) \frac{\partial w}{\partial y}$$

$$\epsilon_{xz} = \frac{1}{2} \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial z} \right), \quad \epsilon_{yz} = \frac{\partial u}{\partial y} + \frac{1}{2} \left(\frac{\partial w}{\partial y} \right)^2$$

$$\epsilon_{yz} = \frac{1}{2} \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial z} \right), \quad \epsilon_{zz} = \frac{\partial w}{\partial z} \quad (5.1-5)$$

بامتردادن رابطه (5.1-5) در (5.1-1) داريم:

$$\varepsilon_{xx} = \frac{\partial u_0}{\partial x} + \frac{1}{2} \left(\frac{\partial w_0}{\partial x} \right)^2 - z \frac{\partial^2 w_0}{\partial x^2}$$

$$\varepsilon_{xy} = \frac{1}{2} \left(\frac{\partial u_0}{\partial y} + \frac{\partial v_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial w_0}{\partial y} \right) - z \frac{\partial^2 w_0}{\partial x \partial y}$$

$$\varepsilon_{yy} = \frac{\partial v_0}{\partial y} + \frac{1}{2} \left(\frac{\partial w_0}{\partial y} \right)^2 - z \frac{\partial^2 w_0}{\partial y^2}$$

$$\varepsilon_{xz} = \frac{1}{2} \left(-\frac{\partial w_0}{\partial x} + \frac{\partial w_0}{\partial x} \right) = 0$$

$$\varepsilon_{yz} = \frac{1}{2} \left(-\frac{\partial w_0}{\partial y} + \frac{\partial w_0}{\partial y} \right) = 0$$

$$\varepsilon_{zz} = 0$$

(5.1-6)

كرستي هاي von Karman

دورمئكالي مرفقي حل شود را ورق
فوئدارين س نامه.

$$\begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{Bmatrix} = \begin{Bmatrix} \varepsilon_x^0 \\ \varepsilon_y^0 \\ \gamma_{xy}^0 \end{Bmatrix} + z \begin{Bmatrix} \varepsilon_x^{(1)} \\ \varepsilon_y^{(1)} \\ \gamma_{xy}^{(1)} \end{Bmatrix} \quad (5.1-7)$$

$$\begin{Bmatrix} \varepsilon_x^0 \\ \varepsilon_y^0 \\ \gamma_{xy}^0 \end{Bmatrix} = \begin{Bmatrix} \frac{\partial u_0}{\partial x} + \frac{1}{2} \left(\frac{\partial w_0}{\partial x} \right)^2 \\ \frac{\partial v_0}{\partial y} + \frac{1}{2} \left(\frac{\partial w_0}{\partial y} \right)^2 \\ \frac{\partial u_0}{\partial y} + \frac{\partial v_0}{\partial x} + \frac{\partial w_0}{\partial x} \frac{\partial w_0}{\partial y} \end{Bmatrix}, \quad \begin{Bmatrix} \varepsilon_x^{(1)} \\ \varepsilon_y^{(1)} \\ \gamma_{xy}^{(1)} \end{Bmatrix} = \begin{Bmatrix} -\frac{\partial^2 w_0}{\partial x^2} \\ -\frac{\partial^2 w_0}{\partial y^2} \\ -2 \frac{\partial^2 w_0}{\partial x \partial y} \end{Bmatrix} \quad (5.1-8)$$

$\{\varepsilon^o\}$: membrane Strain

$\{\varepsilon''\}$: bending strain , curvature

5.1.2 - روابط فضائی حالات حینه لای (CLPT)

$$\begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_6 \end{Bmatrix}_K = \begin{Bmatrix} Q_{11} & Q_{12} & 0 \\ Q_{12} & Q_{22} & 0 \\ 0 & 0 & Q_{66} \end{Bmatrix}_K \begin{Bmatrix} \varepsilon_1 - \alpha_1 \Delta T \\ \varepsilon_2 - \alpha_2 \Delta T \\ \varepsilon_6 \end{Bmatrix}_K - \begin{Bmatrix} 0 & 0 & \varepsilon_{31} \\ 0 & 0 & \varepsilon_{32} \\ 0 & 0 & \varepsilon_{33} \end{Bmatrix}_K \begin{Bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{Bmatrix}_K \quad (5.1.9)$$

ماتریس $\{\varepsilon\}_K$ را صد عیند اللزجی نامند بردار $\{\varepsilon\}_K$ برا
میان اللزجی نامن.

براسی حبیب های غیر ارادی

(۵.۱-۱۰)

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix}^{(k)} = \begin{bmatrix} \bar{Q}_{11} & \bar{Q}_{12} & \bar{Q}_{16} \\ \bar{Q}_{12} & \bar{Q}_{22} & \bar{Q}_{26} \\ \bar{Q}_{16} & \bar{Q}_{26} & \bar{Q}_{66} \end{bmatrix}^{(k)} \left(\begin{Bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \gamma_{xy} \end{Bmatrix} - \begin{Bmatrix} \alpha_{xx} \\ \alpha_{yy} \\ 2\alpha_{xy} \end{Bmatrix} \Delta T \right) \\ - \begin{bmatrix} 0 & 0 & \bar{e}_{31} \\ 0 & 0 & \bar{e}_{32} \\ 0 & 0 & \bar{e}_{36} \end{bmatrix}^{(k)} \begin{Bmatrix} \mathcal{E}_x \\ \mathcal{E}_y \\ \mathcal{E}_z \end{Bmatrix}^{(k)}$$

۳-۱-۳ - معادلات حرکت.

$$\int_0^T (\delta U + \delta V - \delta K) dt = 0 \quad (5.1-11)$$

δU : ارزش کرنی مجازی کل میم

δV : کار مجازی انجام شد، توسط نرخهای خارجی

δK : ارزش جنبشی مجازی

$$I = \int L dt = \int (\pi - K) dt = \text{مینیمیز} \\ \Rightarrow \delta I = 0 \rightarrow \int (\delta \pi - \delta K) dt = 0$$