

بِسْمِ اللّٰهِ الرَّحْمٰنِ الرَّحِیْمِ

مکانیک رست

حلہ ۴

problem $\vec{\nabla} \cdot \vec{D} = ?$

$$\vec{\nabla} \cdot \vec{D} = \left(\vec{e}_k \frac{\partial}{\partial y_k} \right) \cdot \left(D_{ij} \vec{e}_i \otimes \vec{e}_j \right) = \frac{\partial D_{ij}}{\partial y_k} \overbrace{(\vec{e}_k \cdot \vec{e}_i)}^{\delta_{ki}} \vec{e}_j = \frac{\partial D_{ij}}{\partial y_i} \vec{e}_j$$

(a vector)

Problem: $\vec{A} \otimes \vec{B} \rightsquigarrow$ dyadic

$$\begin{aligned} \vec{A} \otimes \vec{B} &= (A_i \vec{e}_i) \otimes (B_j \vec{e}_j) = A_i B_j (\vec{e}_i \otimes \vec{e}_j) = a_{ki} A'_k a_{lj} B'_l (\vec{e}_i \otimes \vec{e}_j) \\ &= A'_k B'_l \vec{e}_k \otimes \vec{e}_l \end{aligned}$$

$$\vec{F} = F_i \vec{e}_i = F'_i \vec{e}'_i$$

$$\vec{F} = m \vec{a}$$

$$F_i = m a_i$$

$$F'_i = m a'_i$$

تعريف: Double-dot product

$$(\vec{A} \otimes \vec{B}) : (\vec{C} \otimes \vec{D}) = (\vec{A} \cdot \vec{C}) (\vec{B} \cdot \vec{D})$$

problem $\vec{\Phi} : \vec{\Psi} = ?$

$$\begin{aligned} &= \Phi_{ij} (\vec{e}_i \otimes \vec{e}_j) : \Psi_{kl} (\vec{e}_k \otimes \vec{e}_l) = \Phi_{ij} \Psi_{kl} (\vec{e}_i \otimes \vec{e}_j) : (\vec{e}_k \otimes \vec{e}_l) \\ &= \Phi_{ij} \Psi_{kl} \underbrace{(\vec{e}_i \cdot \vec{e}_k)}_{\delta_{ik}} \underbrace{(\vec{e}_j \cdot \vec{e}_l)}_{\delta_{jl}} = \Phi_{ij} \Psi_{ij} \end{aligned}$$

$$\vec{\Phi} : \vec{\Psi} = \Phi_{ij} \Psi_{ij}$$

problem $\vec{\Phi} : \vec{I} = ?$

$$= \dots = \Phi_{ii}$$

تمرین سری 1:

$$1- \vec{u} \cdot (\vec{v} \times \vec{w}) = \vec{v} \cdot (\vec{w} \times \vec{u}) = \vec{w} \cdot (\vec{u} \times \vec{v})$$

$$2- \vec{u} \cdot (\vec{u} \times \vec{v}) = 0$$

$$3- \vec{u} \times \vec{v} = \det \begin{bmatrix} e_1 & e_2 & e_3 \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{bmatrix}$$

$$4- (\vec{A} \cdot \vec{B})^T = B^T \cdot A^T$$

$$5- I : \vec{A} = \text{tr}(\vec{A}) = A : I$$

$$6- \vec{A} : (\vec{B} \cdot \vec{C}) = (\vec{B}^T \cdot \vec{A}) : \vec{C} = (\vec{A} \cdot \vec{C}^T) : \vec{B}$$

$$7- (\vec{A} \cdot \vec{B})^{-1} = \vec{B}^{-1} \cdot \vec{A}^{-1}$$

$$8- \vec{S} : \vec{B} = \vec{S} : \vec{B}^T = \vec{S} : \frac{1}{2}(\vec{B} + \vec{B}^T) \quad (S: \text{symmetric tensor})$$

$$9- \vec{S} : \vec{w} = 0 \quad (w: \text{skew (Antisymmetric tensor)})$$

$$10- \vec{A}^{-T} : \vec{A} = 3$$

problem $\vec{e}_i \cdot \vec{A} \cdot \vec{e}_j = ?$

$$= \vec{e}_i \cdot (A_{kl} \vec{e}_k \otimes \vec{e}_l) \cdot \vec{e}_j = A_{kl} \delta_{ik} \delta_{lj}$$

$$= A_{ij}$$

تعريف: Dot production of a dyadic and a dyadic
 $(\vec{u} \otimes \vec{v}) \cdot (\vec{w} \otimes \vec{x}) = (\vec{v} \cdot \vec{w}) (\vec{u} \otimes \vec{x})$
 a dyadic

problem $\vec{A} \cdot \vec{B} = ?$

$$(A_{ij} \vec{e}_i \otimes \vec{e}_j) \cdot (B_{kl} \vec{e}_k \otimes \vec{e}_l)$$

$$= A_{ij} B_{kl} \underbrace{(\vec{e}_j \cdot \vec{e}_k)}_{\delta_{jk}} (\vec{e}_i \otimes \vec{e}_l)$$

$$= A_{ij} B_{jl} \vec{e}_i \otimes \vec{e}_l$$

به عبارت دیگر

$$(A \cdot B)_{ij} = A_{ik} B_{kj}$$

A, B : dyadic

$$\underline{e}_i \cdot (A \cdot B) \cdot \underline{e}_j = \dots = A_{ik} B_{kj}$$

useful properties:

vector: $\underline{u} + \underline{v} = \underline{v} + \underline{u}$

$$(\alpha + \beta) \underline{u} = \alpha \underline{u} + \beta \underline{u}$$

$$\alpha (\underline{u} + \underline{v}) = \alpha \underline{u} + \alpha \underline{v}$$

$$\underline{u} \cdot (\alpha \underline{v} + \beta \underline{w}) = \alpha (\underline{u} \cdot \underline{v}) + \beta (\underline{u} \cdot \underline{w})$$

$$|\underline{u}| = \sqrt{\underline{u} \cdot \underline{u}} = \sqrt{u_i u_i}$$

2^{nd} -order tensors
and dyadics

$$\vec{A} \cdot (\alpha \vec{u} + \vec{v}) = \alpha \vec{A} \cdot \vec{u} + \vec{A} \cdot \vec{v}$$

$$(\vec{A} \pm \vec{B}) \cdot \vec{u} = \vec{A} \cdot \vec{u} \pm \vec{B} \cdot \vec{u}$$

$$(\alpha \vec{A}) \cdot \vec{u} = \alpha (\vec{A} \cdot \vec{u})$$

$$(\alpha \vec{u} + \beta \vec{v}) \otimes \vec{w} = \alpha (\vec{u} \otimes \vec{w}) + \beta (\vec{v} \otimes \vec{w})$$

Dyadics:

$$A + B = B + A$$

A, B, C : dyadics

$$(A \cdot B) \cdot C = A \cdot (B \cdot C) = A \cdot B \cdot C$$

$$A^2 = A \cdot A$$

$$(A + B) \cdot C = A \cdot C + B \cdot C$$

تعريف: Invers of a dyadic

$$A \cdot A^{-1} = I = A^{-1} \cdot A$$

useful properties: $(A^{-1})^{-1} = A$

A: Dyadic

$$(\alpha A)^{-1} = \frac{1}{\alpha} A^{-1}$$

$$(A^{-1})^T = (A^T)^{-1}$$

$$\det(A^{-1}) = (\det(A))^{-1}$$

$$(A \cdot B \cdots Y \cdot Z)^{-1} = Z^{-1} \cdot Y^{-1} \cdots B^{-1} \cdot A^{-1}$$

$$(A \cdot B \cdots Y \cdot Z)^T = Z^T \cdot Y^T \cdots B^T \cdot A^T$$

Symmetric and skew tensors

A: second-order tensor

$$S = \frac{1}{2} (A + A^T)$$

symmetric tensor

$$W = \frac{1}{2} (A - A^T)$$

skew tensor

Useful properties:

B : dyadic

$$S:B = S:B^T = S:\frac{1}{2}(B+B^T)$$

$$W:B = -W:B^T = W:\frac{1}{2}(B-B^T)$$

$$S:W = 0$$

تعريف

adjoint of a dyadic

$$\text{adj}(\vec{A}) = A^{\text{adj}} = \det(A)A^{-1} \quad \left(\equiv \frac{\det(A)}{A} \right)$$

تعريف

cofactor of a dyadic

$$\text{cof}(\vec{A}) = A^{\text{cof}} = \det(A)\vec{A}^T = (A^{\text{adj}})^T$$
$$\left(\equiv \frac{\det(A)}{A^t} \right)$$

1.9 - Higher-order Tensors

$$A_{ij\dots n} \vec{e}_i \otimes \vec{e}_j \dots \otimes \vec{e}_n$$

تعريف $(\vec{u} \otimes \vec{v} \otimes \vec{w}) \cdot \vec{x} = (\vec{w} \cdot \vec{x}) (\vec{u} \otimes \vec{v})$

تعريف $(\vec{u} \otimes \vec{v} \otimes \vec{w}) : (\vec{x} \otimes \vec{y}) = (\vec{v} \cdot \vec{x}) (\vec{w} \cdot \vec{y}) \vec{u}$

problem $(\vec{u} \otimes \vec{v} \otimes \vec{w}) : \vec{I} \stackrel{(\vec{e}_i \otimes \vec{e}_i)}{\sim} = ?$

$$= \dots = (\vec{v} \cdot \vec{w}) \vec{u}$$

تعريف $(\vec{u} \otimes \vec{v} \otimes \vec{w} \otimes \vec{x}) : (\vec{y} \otimes \vec{z}) = (\vec{w} \cdot \vec{y}) (\vec{x} \cdot \vec{z}) (\vec{u} \otimes \vec{v})$

problem: A : a tensor of order four

B : a second-order tensor

$$A : B = A_{ijkl} B_{kl} \vec{e}_i \otimes \vec{e}_j$$

useful properties:

A, B, C, D : 2nd-order tensors

$$(A \otimes B) : C = A (B : C) = (B : C) A$$

$$A : (B \otimes C) = (A : B) C = C (A : B)$$

$$(A \otimes B) : (C \otimes D) = (B : C) (A \otimes D) = (A \otimes D) (B : C)$$

$$A \cdot (B \otimes C) \cdot D = (A \cdot B) \otimes (C \cdot D)$$

تعريف

$\mathbb{I}, \bar{\mathbb{I}}$: fourth-order unit tensor

$$\vec{A} = \mathbb{I} : \vec{A} \quad , \quad \vec{A}^T = \bar{\mathbb{I}} : \vec{A}$$

$$(II)_{ijkl} = \delta_{ik} \delta_{jl} \longrightarrow \mathbb{II} = \delta_{ik} \delta_{jl} \bar{e}_i \otimes \bar{e}_j \otimes \bar{e}_k \otimes \bar{e}_l = \bar{e}_i \otimes \bar{e}_j \otimes \bar{e}_i \otimes \bar{e}_j$$

$$(\bar{II})_{ijkl} = \delta_{il} \delta_{jk} \longrightarrow \bar{\mathbb{II}} = \delta_{il} \delta_{jk} \bar{e}_i \otimes \bar{e}_j \otimes \bar{e}_k \otimes \bar{e}_l = \bar{e}_i \otimes \bar{e}_j \otimes \bar{e}_j \otimes \bar{e}_i$$

تعريف $(A^T)_{ijkl} = A_{kl ij}$

$A, B = 2^{\text{nd}}\text{-order}$ $(A \otimes B)^T = B \otimes A$

تمرین سری ۲

$$1 - \vec{u} \cdot (\vec{S} \cdot \vec{v}) = \vec{v} \cdot (\vec{S}^t \cdot \vec{u})$$

$$2 - (\vec{u} \otimes \vec{v}) \cdot \vec{S} = \vec{u} \otimes \vec{S}^t \cdot \vec{v}$$

$$3 - \text{tr}(\vec{u} \otimes \vec{v}) = (\vec{u} \otimes \vec{v})_{ii} = u_i v_i$$

$$4 - \text{tr}(S^t) = \text{tr}(S)$$

$$5 - \text{tr}(S_1 S_2) = \text{tr}(S_2 S_1)$$

$$6 - A : B = \text{tr}(A^t \cdot B) = \text{tr}(B \cdot A^t) = \text{tr}(B^t \cdot A) = \text{tr}(A \cdot B^t) = A_{ij} B_{ij}$$

$$7 - \text{tr}(S) = I : S$$

$$8 - \text{tr}(I) = 3$$

$$9 - C \cdot (A \otimes B) \cdot D = (C \cdot A) \otimes (B \cdot D)$$

$$10 - S \cdot (\vec{u} \otimes \vec{v}) = S \cdot \vec{u} \otimes \vec{v}$$

$$11 - (\vec{u} \otimes \vec{v}) \cdot S = \vec{u} \otimes S^t \cdot \vec{v}$$

Second-order tensor : D, C, B, A, S

First-order tensor : u, v